

Math 54 Midterm 2 Review

1. Which of the following are vector spaces? (For an extra challenge, for each set that is a vector space, try to figure out its dimension.)
- (a) The set of 5×5 matrices A such that $A^T = A$.
 - (b) The set of linear transformations from \mathbb{R}^3 to \mathbb{R}^2 that are onto.
 - (c) The set of all polynomials with coefficients in the real numbers that have the form $ax^3 + bx$.
 - (d) The set of convergent sequences of real numbers.

- (a) Vector space.
- (b) Not a vector space. For instance, it does not contain the linear transformation that maps all vectors to $\mathbf{0}$ (which is the zero vector in the vector space of all linear transformations from \mathbb{R}^3 to \mathbb{R}^2).
- (c) Vector space.
- (d) Vector space.

2. Let V be the subspace of the vector space of continuous functions that is spanned by the set $\{\sin(x), \cos(x), e^{e^x}\}$ (you may assume without proof that these three functions are linearly independent). Do the functions f, g, h form a basis for V ?

$$\begin{aligned} f(x) &= 3 \sin(x) + 2 \cos(x) + e^{e^x} \\ g(x) &= \sin(x) + 2 \cos(x) \\ h(x) &= 5 \sin(x) + 6 \cos(x) + e^{e^x} \end{aligned}$$

Note that the set $\mathcal{B} = \{\sin(x), \cos(x), e^{e^x}\}$ forms a basis for V . So we can write everything as a coordinate vector in this basis and use the fact that \mathbb{R}^3 is isomorphic to V .

$$[f]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} \quad [g]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \quad [h]_{\mathcal{B}} = \begin{bmatrix} 5 \\ 6 \\ 1 \end{bmatrix}$$

To check if these three vectors in \mathbb{R}^3 are a basis, we can write them as the columns of a matrix and check if it has a pivot in every row.

$$\begin{bmatrix} 3 & 1 & 5 \\ 2 & 2 & 6 \\ 1 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 4 \\ 0 & 1 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

Since this matrix does not have a pivot in every row, $\{[f]_{\mathcal{B}}, [g]_{\mathcal{B}}, [h]_{\mathcal{B}}\}$ does not form a basis for \mathbb{R}^3 so $\{f, g, h\}$ does not form a basis for V .

3. Let $\mathcal{B} = \{1 + x, x + x^2, 1 + x^2\}$, $\mathcal{C} = \{1 + x + x^2, 2 + x + x^2, 3x^2\}$ and $T: \mathbb{P}_2 \rightarrow \mathbb{R}^2$ be the linear transformation defined by

$$T(p) = \begin{bmatrix} p(2) \\ p(1) + p(3) \end{bmatrix}.$$

- (a) Find the matrix for T relative to \mathcal{B} and the standard basis of \mathbb{R}^2 .
 (b) Find the change of basis matrix from \mathcal{C} to \mathcal{B} .
 (c) Use your answers to parts (a) and (b) to find the matrix for T relative to \mathcal{C} and the standard basis for \mathbb{R}^2 .

(a)

$$\varepsilon[T]_{\mathcal{B}} = [[T(1+x)]_{\mathcal{E}} [T(x+x^2)]_{\mathcal{E}} [T(1+x^2)]_{\mathcal{E}}] = \begin{bmatrix} 3 & 6 & 5 \\ 6 & 14 & 12 \end{bmatrix}$$

- (b) To solve this problem, we will write everything as a coordinate vector in the basis $\mathcal{D} = \{1, x, x^2\}$ and then solve the problem in \mathbb{R}^3 in the usual way. If we do this, we simply need to find the change of basis matrix from the basis of \mathbb{R}^3 consisting of the columns of matrix B (where the columns of B are the vectors in \mathcal{C} written as coordinate vectors in basis \mathcal{D}) to the basis of \mathbb{R}^3 consisting of the columns of matrix A (where the columns of A are the vectors in \mathcal{B} written as coordinate vectors in basis \mathcal{D}).

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 2 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

The change of basis matrix is just $A^{-1}B$, and one way to find it is to row reduce $[A \mid B]$ to $[I \mid A^{-1}B]$. This gives us the matrix

$$P_{\mathcal{B} \leftarrow \mathcal{C}} = \begin{bmatrix} 1/2 & 1 & -3/2 \\ 1/2 & 0 & 3/2 \\ 1/2 & 1 & 3/2 \end{bmatrix}$$

(c)

$$\varepsilon[T]_{\mathcal{B}} = \varepsilon[T]_{\mathcal{B}} P_{\mathcal{B} \leftarrow \mathcal{C}} = \begin{bmatrix} 7 & 8 & 12 \\ 16 & 18 & 30 \end{bmatrix}$$

4. Let \mathbf{v} and \mathbf{u} be eigenvectors of a matrix A with different eigenvalues. Show that $\mathbf{u} + \mathbf{v}$ is not an eigenvector of A .

Let λ and μ be the eigenvalues corresponding to \mathbf{v} and \mathbf{u} respectively. Suppose for contradiction that $\mathbf{u} + \mathbf{v}$ is an eigenvector of A and let γ be the corresponding eigenvalue. Then we have

$$A(\mathbf{v} + \mathbf{u}) = A\mathbf{v} + A\mathbf{u} = \lambda\mathbf{v} + \mu\mathbf{u}$$

and

$$A(\mathbf{v} + \mathbf{u}) = \gamma(\mathbf{v} + \mathbf{u}) = \gamma\mathbf{v} + \gamma\mathbf{u}.$$

Subtracting these two equations gives us

$$\mathbf{0} = (\lambda - \gamma)\mathbf{v} + (\mu - \gamma)\mathbf{u}.$$

Since \mathbf{v} and \mathbf{u} are eigenvectors for distinct eigenvalues, then as shown in class they are linearly independent. Thus we must have $\lambda - \gamma = 0$ and $\mu - \gamma = 0$. But this implies that $\lambda = \gamma$ and $\mu = \gamma$, contradicting the assumption that $\lambda \neq \mu$.

5. Let $\mathbf{v}_1, \dots, \mathbf{v}_k$ be eigenvectors of a matrix A with distinct eigenvalues. Show that no linear combination of $\mathbf{v}_1, \dots, \mathbf{v}_k$ is an eigenvector of A .

This problem is not quite correct as stated: \mathbf{v}_1 is a linear combination of $\mathbf{v}_1, \dots, \mathbf{v}_k$ and it is an eigenvector of A . The problem should have stated that a linear combination of $\mathbf{v}_1, \dots, \mathbf{v}_k$ can only be an eigenvector of A if it is simply a multiple of one of the \mathbf{v}_i (i.e. all but one of the coefficients are 0).

Let a_1, \dots, a_n be scalars such that at least two of the a_i are nonzero. Without loss of generality, we assume that a_1 and a_2 are nonzero. Let $\mathbf{x} = a_1\mathbf{v}_1 + \dots + a_n\mathbf{v}_n$. Suppose for contradiction that \mathbf{x} is an eigenvector of A , with eigenvalue γ . Then we have

$$A\mathbf{x} = \gamma\mathbf{x} = \gamma(a_1\mathbf{v}_1 + \dots + a_n\mathbf{v}_n) = \gamma a_1\mathbf{v}_1 + \dots + \gamma a_n\mathbf{v}_n$$

And on the other hand we have

$$A\mathbf{x} = A(a_1\mathbf{v}_1 + \dots + a_n\mathbf{v}_n) = \lambda_1 a_1\mathbf{v}_1 + \dots + \lambda_n a_n\mathbf{v}_n$$

Subtracting the second equation from the first gives us

$$\mathbf{0} = (\gamma - \lambda_1)a_1\mathbf{v}_1 + \dots + (\gamma - \lambda_n)a_n\mathbf{v}_n$$

Since $\mathbf{v}_1, \dots, \mathbf{v}_n$ are eigenvectors of A with distinct eigenvalues, they are linearly independent. Thus the above equation implies that for each i , $(\gamma - \lambda_i)a_i = 0$. And if $a_i \neq 0$ this implies that $\gamma - \lambda_i = 0$ and thus that $\gamma = \lambda_i$. Since a_1 and a_2 are both nonzero by assumption, we have $\lambda_1 = \gamma = \lambda_2$, contradicting the assumption that λ_1 and λ_2 are distinct.

6. Suppose A is a 5×5 matrix whose characteristic polynomial is $\lambda^3(\lambda - 1)(\lambda - 2)$. What are the possible values for rank A ? For which of these values is A diagonalizable?

Since the multiplicity of 0 as an eigenvalue of A is 3, the eigenspace $\text{Null}(A - 0I) = \text{Null } A$ has dimension at least 1 and at most 3. By the rank theorem, this implies that $\text{rank } A$ is between $5 - 3 = 2$ and $5 - 1 = 4$. Since A is diagonalizable if and only if the dimension of its eigenspaces adds up to 5, it is diagonalizable if and only if $\text{Null } A$ has dimension 3. Thus A is diagonalizable if and only if $\text{rank } A$ is 2.

7. Find a formula for A^n where

$$A = \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}.$$

Diagonalize A . To compute the eigenvalues we can find the characteristic polynomial or note that it is upper triangular, so the eigenvalues are the entries along the diagonal— 2 and 3. Now we need to find an eigenvector basis.

$$E_2 = \text{Null}(A - 2I) : A - 2I = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$E_3 = \text{Null}(A - 3I) : A - 3I = \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$$

So two linearly independent eigenvectors (with eigenvalues 2 and 3 respectively) are

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Thus we can write

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}^{-1}$$

And therefore we have

$$\begin{aligned} A^n &= \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2^n & 0 \\ 0 & 3^n \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2^n & 0 \\ 0 & 3^n \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 2^n & 3^n - 2^n \\ 0 & 3^n \end{bmatrix} \end{aligned}$$

8. Mark each of the following statements true or false. For each statement, either give a proof that it is always true or give a counterexample to show it can be false.

- (a) Let A be an $n \times n$ matrix with only positive eigenvalues such that there is an orthogonal basis for \mathbb{R}^n consisting of eigenvectors of A . If \mathbf{x} is a nonzero vector then $\mathbf{x} \cdot (A\mathbf{x})$ is positive.

- (b) Every diagonalizable matrix is invertible.
 (c) Every invertible matrix is diagonalizable.
 (d) Every matrix with a repeated eigenvalue is not diagonalizable.
 (e) Let V be a subspace of \mathbb{R}^n and W a subspace of V . Let \mathbf{x} be a vector in \mathbb{R}^n , \mathbf{y} the projection of \mathbf{x} on the subspace V and \mathbf{z} the projection of \mathbf{y} on the subspace W . Then \mathbf{z} is the projection of \mathbf{x} on W .
 (f) If \mathbf{v} and \mathbf{u} are eigenvectors of a matrix A with distinct eigenvalues then \mathbf{v} and \mathbf{u} are orthogonal.

Note: on an exam you should actually prove that your counterexamples are in fact valid counterexamples.

- (a) True. Let $\mathbf{v}_1, \dots, \mathbf{v}_n$ be an orthogonal basis of \mathbb{R}^n consisting of eigenvectors of A with corresponding eigenvalues $\lambda_1, \dots, \lambda_n$. Let \mathbf{x} be any nonzero vector. Since the \mathbf{v}_i 's form a basis, there exist scalars c_1, \dots, c_n such that $\mathbf{x} = c_1\mathbf{v}_1 + \dots + c_n\mathbf{v}_n$. We have

$$\begin{aligned}\mathbf{x} \cdot (A\mathbf{x}) &= (c_1\mathbf{v}_1 + \dots + c_n\mathbf{v}_n) \cdot (A(c_1\mathbf{v}_1 + \dots + c_n\mathbf{v}_n)) \\ &= (c_1\mathbf{v}_1 + \dots + c_n\mathbf{v}_n) \cdot (\lambda_1c_1\mathbf{v}_1 + \dots + \lambda_nc_n\mathbf{v}_n)\end{aligned}$$

By linearity of the dot product in each coordinate and by orthogonality of the \mathbf{v}_i 's, this is equal to

$$= \lambda_1c_1^2(\mathbf{v}_1 \cdot \mathbf{v}_1) + \dots + \lambda_nc_n^2(\mathbf{v}_n \cdot \mathbf{v}_n)$$

which is always nonnegative, and positive as long as one of the c_i 's is nonzero (which must be the case if \mathbf{x} is nonzero).

- (b) False. Counterexample: $\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$.
 (c) False. Counterexample: $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$.
 (d) False. Counterexample: $\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$.
 (e) True. Let $\mathbf{y}' = \mathbf{x} - \mathbf{y}$ and let $\mathbf{z}' = \mathbf{y} - \mathbf{z}$. So as we have seen in class, $\mathbf{y}' \in V^\perp$ and $\mathbf{z}' \in W^\perp$. Since $W \subseteq V$, \mathbf{y}' is also perpendicular to everything in W —i.e. $\mathbf{y}' \in W^\perp$. By a homework exercise, W^\perp is a subspace and so $\mathbf{y}' + \mathbf{z}' \in W^\perp$. So we have

$$\mathbf{x} = \mathbf{z} + (\mathbf{z}' + \mathbf{y}')$$

where $\mathbf{z} \in W$ and $\mathbf{z}' + \mathbf{y}' \in W^\perp$. Since the decomposition of \mathbf{x} into an element of W and an element of W^\perp is unique, we must have $\mathbf{z} = \text{Proj}_W(\mathbf{x})$.

- (f) False. Take any two vectors that are linearly independent and not orthogonal. Define a linear transformation for which both vectors are eigenvectors. As an example, take the two vectors to be $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and let $P = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$. Then $A = P \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} P^{-1}$ has the two chosen vectors as eigenvectors.