# MONOTONE LINKS IN DAHA AND EHA 

PAVEL GALASHIN AND THOMAS LAM


#### Abstract

We define monotone links on a torus, obtained as projections of curves in the plane whose coordinates are monotone increasing. Using the work of Morton-Samuelson, to each monotone link we associate elements in the double affine Hecke algebra and the elliptic Hall algebra. In the case of torus knots (when the curve is a straight line), we recover symmetric function operators appearing in the rational shuffle conjecture.

We show that the class of monotone links viewed as links in $\mathbb{R}^{3}$ coincides with the class of Coxeter links, studied by Oblomkov-Rozansky in the setting of the flag Hilbert scheme. When the curve satisfies a convexity condition, we recover positroid links that we previously studied. In the convex case, we conjecture that the associated symmetric functions are Schur positive, extending a recent conjecture of Blasiak-Haiman-Morse-Pun-Seelinger, and we speculate on the relation to Khovanov-Rozansky homology.

Our constructions satisfy a skein recurrence where the base case consists of piecewise almost linear curves. We show that convex piecewise almost linear curves give rise to algebraic links.


## 1. Introduction

Cherednik Che13, reinterpreting earlier work of Aganagic and Shakirov AS15, constructed elements in the double affine Hecke algebra (DAHA) associated to an ( $m, n$ )-torus knot, with the aim of constructing triply-graded link homology. This construction was expanded on in the influential work of Gorsky and Neguţ GN15], who further constructed elements in the elliptic Hall algebra (EHA) using the work of Schiffmann and Vasserot SV11, SV13. These objects appear at the intersection of beautiful conjectures relating link homology, compactified Jacobians, Hilbert schemes, rational Cherednik algebras, symmetric functions, cluster algebras, and braid varieties; see GNR21, GM13, CD16, ORS18, OY17, OR17, GORS14, FPST22, STWZ19, GL20, CGGS21, GLSBS22, GLSB23, CGG+22].

There are multiple indications that these algebraic constructions extend beyond the case of torus knots. For instance, some of the conjectures mentioned above extend to the case of algebraic knots and links CD17, ORS18, KT22]. In another direction, OblomkovRozansky OR17] related the homology of Coxeter links (which include torus knots and torus links) to the space of sections of a line bundle on a Hilbert scheme of points in $\mathbb{C}^{2}$.

In this work, we study DAHA, EHA, and symmetric function invariants for the class of monotone links which includes torus knots and torus links. A monotone link is a projection (under the map $\mathbb{R}^{2} \rightarrow \mathbb{R}^{2} / \mathbb{Z}^{2}$ ) of a curve $C$ from $(0,0)$ to $(m, n)$ with both coordinates

[^0]monotone increasing; see Section 1.2. Our construction depends on viewing monotone links as links in a (thickened) torus. It turns out that viewing them as links in $\mathbb{R}^{3}$ instead, one recovers precisely the Coxeter links of OR17; see Sections 7.2 and 7.3 .

In our earlier works [GL20, GL21, GL22], we studied positroid links associated to the positroid stratification of the Grassmannian and discovered that the associated combinatorics involves Dyck paths under an arbitrary convex curve. This surprising convexity property of positroid links was a starting point for this work. Around the same time, Blasiak-Haiman-Morse-Pun-Seelinger $\left[\mathrm{BHM}^{+} 21\right]$ constructed symmetric functions in the context of the shuffle conjecture [HHL ${ }^{+}$05, BGLX15, GN15, CM18, Mel16] and independently conjectured that under a convexity assumption, these symmetric functions are Schur positive.

We showed in [GL21] that for each repetition-free positroid link, the Euler characteristic of the associated positroid variety equals the number of Dyck paths below a convex curve $C$, and that any convex curve appears in this way. Our proof relied on a Dyck path recurrence involving three curves passing above, below, and through a lattice point, respectively. One of our main results is a lift of this Dyck path recurrence to the $q, t$-level; see Theorem 1.7 .

Our main conjecture (Conjecture 1.13) states that convex monotone links produce Schur positive symmetric functions. We show that under the specialization $t=q^{-1}$, we recover the HOMFLY polynomial of the link, and we give an explicit formula for our symmetric function when $t=1$. We further conjecture that our invariants recover Khovanov-Rozansky link homology in the case of algebraic links. For the case of torus links with multiple components, we expect that our conjecture coincides with that of Cherednik-Danilenko [CD17] who more generally studied iterated torus cables.

To produce our invariants, we apply the construction of Morton-Samuelson MS17, MS21], who connected the skein algebra of the torus and of the punctured torus to the DAHA and the EHA. At the heart of the technical challenge is the choice of a location for the puncture when lifting our links to the punctured torus; see (1.2).
1.1. Overview. Let $m, n$ be positive integers. A monotone curve (or simply a curve) is the graph of a strictly increasing continuous function $f:[0, m] \rightarrow[0, n]$ satisfying $f(0)=0$ and $f(m)=n$. Given a curve $C$, all of our constructions depend only on the sets of lattice points in $[0, m] \times[0, n]$ which are strictly above, strictly below, and on $C$.

We compute the image of a curve $C$ inside the commutative diagram in Figure 1, where:

- $\mathbb{D}$ is a (two-dimensional) disk, $\mathbb{A}$ is an annulus, $\mathbb{T}$ is a torus, and $\mathbb{T}-\mathbb{D}$ is a punctured torus;
- $\mathrm{Sk}_{q^{-1}}(\mathbb{S})$ is the skein algebra of a surface $\mathbb{S}$;
- $\Lambda_{q}$ and $\Lambda_{q, t}$ are the algebras of symmetric functions over $\mathbb{C}\left(q^{1 / 2}\right)$ and $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)$;
- $\mathbf{S} \ddot{H}_{N: q, t}$ is the spherical DAHA;
- $\mathcal{E}_{q, t}$ is the EHA;
- the superscript ${ }^{+}$denotes the positive part of the corresponding algebra.

The full background on the above objects is given in the main body of the paper. Some examples of symmetric functions in $\Lambda_{q, t}$ associated to curves can be found in Table 1. We now explain our results in more detail.
1.2. Links. Given a curve $C$, let $(0,0)=\boldsymbol{p}_{0}, \boldsymbol{p}_{1}, \ldots, \boldsymbol{p}_{k}=(m, n)$ be the lattice points on $C$ listed from left to right. For $i=1,2, \ldots, k$, let $C_{i}$ be the part of $C$ connecting $\boldsymbol{p}_{i-1}$ to $\boldsymbol{p}_{i}$. The curves $C_{1}, C_{2}, \ldots, C_{k}$ are called the lattice segments of $C$, and we write $C=\left[C_{1} C_{2} \cdots C_{k}\right]$.


Figure 1. A commutative diagram. See Figure 10 for a description of each map.

We denote $\mathrm{k}(C):=k$. We say that $C$ is primitive if $\mathrm{k}(C)=1$, i.e., if $C$ passes through no lattice points in the interior of $[0, m] \times[0, n]$.

Let $\mathbb{T}=\mathbb{R}^{2} / \mathbb{Z}^{2}$ be the torus and $\pi: \mathbb{R}^{2} \rightarrow \mathbb{T}$ be the quotient map. To a curve $C$, we associate a link $L_{C}$ in $\mathbb{T} \times[0,1]$, whose link diagram is drawn on $\mathbb{T}$. Suppose first that $C$ is primitive. Consider the projection $\bar{C}:=\pi(C)$ of $C$ to $\mathbb{T}$. Thus, $\bar{C}$ is a curve of homology class $(m, n)$. To convert it into a link diagram of $L_{C}$, for each self-intersection of $\bar{C}$ involving projections of points $\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right) \in[0, m] \times[0, n]$ with $x_{1}<x_{2}$, we draw the segment containing $\left(x_{1}, y_{1}\right)$ below the segment containing $\left(x_{2}, y_{2}\right)$.

Alternatively, if a primitive curve $C$ is a plot of an increasing function $f:[0, m] \rightarrow[0, n]$ then the link $L_{C}$ is a concatenation of two curves in $\mathbb{T} \times[0,1]$ : the curve $(\pi(x, f(x)), x / m)$, $x \in[0, m]$, and the vertical line segment connecting $((0,0), 1)$ to $((0,0), 0)$.

The point $\pi(0,0)=\pi(m, n) \in \mathbb{T}$ is called the corner of $C$.
If $C=\left[C_{1} C_{2} \cdots C_{k}\right]$ is not necessarily primitive, the link $L_{C}$ will have $k$ components $L_{C_{1}}, L_{C_{2}}, \ldots, L_{C_{k}}$. The link diagrams of $L_{C_{1}}, L_{C_{2}}, \ldots, L_{C_{k}}$ are drawn on top of each other so that for $i<j, L_{C_{i}}$ is drawn below $L_{C_{j}}$.
1.3. Skein of a punctured torus. Given an oriented surface $\mathbb{S}$, the skein algebra $\mathrm{Sk}_{t}(\mathbb{S})$ is the algebra of linear combinations of (isotopy classes of oriented) links inside $\mathbb{S} \times[0,1]$ subject to the HOMFLY skein relation ${ }^{1]}$

$$
\begin{equation*}
\left.\boldsymbol{X}-\boldsymbol{X}=\left(t^{1 / 2}-t^{-1 / 2}\right)\right)(. \tag{1.1}
\end{equation*}
$$

The multiplication in $\mathrm{Sk}_{t}(\mathbb{S})$ is given by "stacking the links on top of each other in the $[0,1]$ direction," i.e., by applying the homeomorphism $(\mathbb{S} \times[0,1]) \cup(\mathbb{S} \times[1,2])=\mathbb{S} \times[0,2] \cong \mathbb{S} \times[0,1]$.

Given a curve $C=\left[C_{1} C_{2} \cdots C_{k}\right]$, the link $L_{C}$ may be naturally viewed as an element of $\mathrm{Sk}_{t}(\mathbb{T})$ which we denote $C^{\mathbb{T}}$, and we have

$$
C^{\mathbb{T}}=C_{1}^{\mathbb{T}} \cdot C_{2}^{\mathbb{T}} \cdots C_{k}^{\mathbb{T}}
$$

For example, in Figure 2, $C^{\mathbb{T}}=C_{1}^{\mathbb{T}} \cdot C_{2}^{\mathbb{T}}$ is obtained by drawing $C_{2}^{\mathbb{T}}$ on top of $C_{1}^{\mathbb{T}}$.

[^1]

Figure 2. Projecting a curve to the torus (Section 1.3). In the projection, the red and blue segments of the curve are slightly shifted up for clarity.

Let $\mathbb{T}-\mathbb{D}$ be the punctured torus, obtained by removing a small disk $\mathbb{D}$ from $\mathbb{T}$. Our main construction associates an element of $\mathrm{Sk}_{t}(\mathbb{T}-\mathbb{D})$ to a curve $C$. More precisely, we will work with

$$
\mathrm{Sk}_{q, t}(\mathbb{T}-\mathbb{D}):=\mathrm{Sk}_{t}(\mathbb{T}-\mathbb{D}) \otimes \mathbb{C}\left(q^{1 / 2}\right)
$$

Fix a small $\epsilon>0$ and suppose that $\mathbb{T}-\mathbb{D}$ is obtained by removing a ball of radius $\epsilon / 2$ around $(0,0)$ from $\mathbb{T}$. Let $C$ be a primitive curve, and let $C_{+}:=C+(-\epsilon, \epsilon)$ and $C_{-}:=C+(\epsilon,-\epsilon)$. When projecting $C_{ \pm}$to $\mathbb{T}$, the puncture in $\mathbb{T}-\mathbb{D}$ will be slightly below the corner of $C_{+}$and slightly above the corner of $C_{-}$. Viewing the links $L_{C_{ \pm}}$as elements of the skein $\mathrm{Sk}_{t}(\mathbb{T}-\mathbb{D})$, we obtain elements $C_{ \pm}^{\mathbb{T}-\mathbb{D}} \in \mathrm{Sk}_{t}(\mathbb{T}-\mathbb{D})$. We define

$$
\begin{equation*}
C^{\mathbb{T}-\mathbb{D}}:=\frac{1}{1-q}\left(C_{+}^{\mathbb{T}-\mathbb{D}}-q C_{-}^{\mathbb{T}-\mathbb{D}}\right) \quad \in \mathrm{Sk}_{q, t}(\mathbb{T}-\mathbb{D}) \tag{1.2}
\end{equation*}
$$

If $C=\left[C_{1} C_{2} \cdots C_{k}\right]$ is not necessarily primitive, we set

$$
\begin{equation*}
C^{\mathbb{T}-\mathbb{D}}:=C_{1}^{\mathbb{T}-\mathbb{D}} \cdot C_{2}^{\mathbb{T}-\mathbb{D}} \cdots C_{k}^{\mathbb{T}-\mathbb{D}} \tag{1.3}
\end{equation*}
$$

Remark 1.1. There is a natural algebra homomorphism $\mathrm{Sk}_{q, t}(\mathbb{T}-\mathbb{D}) \rightarrow \mathrm{Sk}_{q^{-1}}(\mathbb{T})$ obtained by setting $t=q^{-1}$ and filling in the puncture $\mathbb{D}$. For any curve $C$, this map sends $C^{\mathbb{T}-\mathbb{D}} \mapsto C^{\mathbb{T}}$.
Remark 1.2. Recall that $\mathbb{A}$ denotes the annulus. Then $\mathbb{A} \times[0,1]$ is homeomorphic to the solid torus, and thus we have a natural action of $\mathrm{Sk}_{q^{-1}}(\mathbb{T})$ on $\mathrm{Sk}_{q^{-1}}(\mathbb{A})$ by identifying $\mathbb{T}$ with the boundary of the solid torus. It is well known (see Theorem 5.2) that the skein of $\mathbb{A}$ may be identified with the algebra $\Lambda_{q}$ of symmetric functions. Thus, each curve $C$ gives rise to a symmetric function $C^{\mathbb{T}} \cdot 1 \in \Lambda_{q}$ which is the $t=q^{-1}$-specialization of the symmetric function $F_{C} \in \Lambda_{q, t}$ of interest to us, defined in (1.10).
1.4. DAHA and EHA elements. Morton and Samuelson [MS21, Theorem 5.7] (see also [BCMN23, Theorem 5.10]) construct a map from the skein of $\mathbb{T}-\mathbb{D}$ to the EHA. This map is obtained by constructing, for each $N=1,2, \ldots$, a map from the skein of $\mathbb{T}-\mathbb{D}$ to the spherical part of the DAHA $\ddot{\mathbf{H}}_{N ; q, t}$, and then taking a limit as $N \rightarrow \infty$. We compute the images of $C^{\mathbb{T}-\mathbb{D}}$ inside the DAHA and the EHA under the maps of [MS21].

By definition, $\ddot{\mathbf{H}}_{N ; q, t}$ is a $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)$-algebra generated by elements $X_{i}^{ \pm 1}, Y_{i}^{ \pm 1}$ for $i=$ $1, \ldots, N$ and $T_{i}^{ \pm 1}$ for $i=1, \ldots, N-1$ satisfying certain relations (see Section 2.1). The spherical DAHA $\mathbf{S H}_{N ; q, t}$ is defined by $\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}:=\boldsymbol{e}_{N} \ddot{\mathbf{H}}_{N ; q, t} \boldsymbol{e}_{N}$, where $\boldsymbol{e}_{N} \in \mathbf{H}_{N ; q, t}$ is a symmetrizing idempotent satisfying $\boldsymbol{e}_{N}^{2}=\boldsymbol{e}_{N}$ and $T_{i} \boldsymbol{e}_{N}=\boldsymbol{e}_{N} T_{i}=t^{-1 / 2} \boldsymbol{e}_{N}$ for all $i$; see 2.8).


Figure 3. Monotone curves from $(0,0)$ to $(2,2)$ and their projections to the torus.

Denote

$$
\begin{equation*}
\gamma_{N ; t}:=1-t^{N} \quad \text { and } \quad \delta_{q, t}:=\frac{1}{t^{1 / 2}(1-q)} \tag{1.4}
\end{equation*}
$$

Definition 1.3. For a curve $C$, let $\mathcal{P}_{C}$ be the highest up-right lattice path from $(0,0)$ to $(m, n)$ staying weakly below $C$. We construct an element $D_{C}^{(N)} \in \mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$ obtained by traversing $\mathcal{P}_{C}$ from $(0,0)$ to $(m, n)$, and taking the product of the following elements:

- $\gamma_{N ; t} \boldsymbol{e}_{N}$ for each lattice point of $C \cap \mathcal{P}_{C}$ other than $(m, n)$;
- $\boldsymbol{e}_{N}$ for the lattice point $(m, n)$;
- $Y_{1}$ for each up step of $\mathcal{P}_{C}$;
- $Y_{1} X_{1} Y_{1}^{-1}$ for each right step of $\mathcal{P}_{C}$.

Example 1.4. For the three curves $C_{+}, C_{-}, C_{0}$ shown in Figure 3, we have $\mathcal{P}_{C_{+}}=R U R U$, $\mathcal{P}_{C_{-}}=R R U U$, and $\mathcal{P}_{C_{0}}=R U * R U$, where $R$ and $U$ indicate right and up steps and $*$ indicates the places where the curve passes through a lattice point other than $(0,0)$ and $(m, n)$. We have
$D_{C_{+}}^{(N)}=\gamma_{N ; t} \boldsymbol{e}_{N} Y_{1} X_{1} Y_{1} X_{1} \boldsymbol{e}_{N}, \quad D_{C_{-}}^{(N)}=\gamma_{N ; t} \boldsymbol{e}_{N} Y_{1} X_{1} X_{1} Y_{1} \boldsymbol{e}_{N}, \quad D_{C_{0}}^{(N)}=\gamma_{N ; t}^{2} \boldsymbol{e}_{N} Y_{1} X_{1} \boldsymbol{e}_{N} Y_{1} X_{1} \boldsymbol{e}_{N}$.
We are ready to state our first main result.
Theorem 1.5. Let $C$ be a curve. The image of $C^{\mathbb{T}-\mathbb{D}}$ under the map

$$
\begin{equation*}
\mathrm{Sk}_{q, t}^{+}(\mathbb{T}-\mathbb{D}) \rightarrow \mathbf{S} \ddot{\mathrm{H}}_{N ; q, t}^{+} \tag{1.5}
\end{equation*}
$$

of [MS21] is given by

$$
\begin{equation*}
\delta_{q, t}^{\mathrm{k}(C)} D_{C}^{(N)} \tag{1.6}
\end{equation*}
$$

The elements $C_{ \pm}^{\mathbb{T}-\mathbb{D}}$ belong to the positive part $\mathrm{Sk}_{t}^{+}(\mathbb{T}-\mathbb{D})$ of $\mathrm{Sk}_{t}(\mathbb{T}-\mathbb{D})$ defined in Section 5.1.4, while the elements $D_{C}^{(N)} \in \mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$ belong to the positive part $\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}^{+}$of $\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$ defined in (3.5). By [SV11, Theorem 4.6], the positive part $\mathcal{E}_{q, t}^{+}$of the EHA can be realized as a limit of $\mathbf{S} \ddot{H}_{N ; q, t}^{+}$as $N \rightarrow \infty$.
Theorem 1.6. Let $C$ be a curve. The elements $D_{C}^{(N)} \in \mathbf{S H}_{N ; q, t}^{+}$for $N=1,2, \ldots$ give rise to a well-defined limiting element

$$
\begin{equation*}
\lim _{N \rightarrow \infty} D_{C}^{(N)}=D_{C} \in \mathcal{E}_{q, t}^{+} . \tag{1.7}
\end{equation*}
$$

An explicit algorithm for expressing $D_{C}$ in terms of the standard generators of $\mathcal{E}_{q, t}^{+}$is given in Section 4. An immediate consequence of Definition 1.3 (using that $\boldsymbol{e}_{N}^{2}=\boldsymbol{e}_{N}$ ) is that for any curve $C=\left[C_{1} C_{2} \cdots C_{k}\right]$, the elements $D_{C}^{(N)}$ and therefore $D_{C}$ satisfy

$$
\begin{equation*}
D_{C}^{(N)}=D_{C_{1}}^{(N)} \cdot D_{C_{2}}^{(N)} \cdots D_{C_{k}}^{(N)} \quad \text { and } \quad D_{C}=D_{C_{1}} \cdot D_{C_{2}} \cdots D_{C_{k}} \tag{1.8}
\end{equation*}
$$

where the products are taken in $\mathbf{S} \ddot{H}_{N ; q, t}^{+}$and $\mathcal{E}_{q, t}^{+}$, respectively.
1.5. Skein relation and piecewise almost linear curves. It turns out that the elements $D_{C}^{(N)}$ and $D_{C}$ satisfy the following skein relation.

Theorem 1.7. Consider curves $C_{+}, C_{-}, C_{0}$ which pass above, below, and through some lattice point $\boldsymbol{p}$, respectively, and agree outside a small neighborhood of $\boldsymbol{p}$. Then

$$
\begin{equation*}
D_{C_{+}}^{(N)}=q t D_{C_{-}}^{(N)}+D_{C_{0}}^{(N)} \quad \text { and } \quad D_{C_{+}}=q t D_{C_{-}}+D_{C_{0}} . \tag{1.9}
\end{equation*}
$$

This relation allows one to express any element $D_{C}$ in terms of elements associated to piecewise almost linear curves, defined as follows.

Definition 1.8. A primitive curve $C$ from $(0,0)$ to $(m, n)$ is called $(m, n)$-almost linear, or simply almost linear, if it passes just above the diagonal connecting $(0,0)$ and $(m, n)$. (That is, it passes above each of the $\operatorname{gcd}(m, n)-1$ lattice points in the interior of the diagonal, and above/below all lattice points which are strictly below/above the diagonal.)

As we explain in Section 7.1, for $C$ an almost linear curve, the operators $D_{C}$ are exactly the symmetric function operators appearing in various versions of the shuffle conjecture.

Definition 1.9. A curve $C=\left[C_{1} C_{2} \cdots C_{k}\right]$ is called piecewise almost linear if each lattice segment $C_{i}$ of $C$ is almost linear.

Remark 1.10. Applying (1.9) repeatedly, we may express the element $D_{C}$ for an arbitrary curve $C$ as a linear combination of elements of the form $D_{C^{\prime}}$, where $C^{\prime}$ is a piecewise almost linear curve. Combining this with (1.8) allows one to express an arbitrary element $D_{C}$ in terms of products of elements $D_{C_{i}^{\prime}}$ corresponding to almost linear curves $C_{i}^{\prime}$.
1.6. Symmetric functions. The EHA $\mathcal{E}_{q, t}^{+}$acts on the ring $\Lambda_{q, t}$ of symmetric functions over $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)$ as described in Section 3.3. We will be particularly interested in the action $D_{C} \cdot 1$ of $D_{C}$ on $1 \in \Lambda_{q, t}$. The DAHA admits a polynomial representation described in Section 2.2 . For $N=1,2, \ldots$, the element $D_{C}^{(N)} \cdot 1$ is a symmetric polynomial in $x_{1}, \ldots, x_{N}$ obtained from the symmetric function $D_{C} \cdot 1$ by setting $x_{N+1}=x_{N+2}=\cdots=0$.

It is convenient to consider the plethystically transformed (cf. Section 7) symmetric functions

$$
\begin{equation*}
F_{C}:=\left(D_{C} \cdot 1\right)\left[\frac{\mathbf{X}}{1-t}\right] \in \Lambda_{q, t} \tag{1.10}
\end{equation*}
$$

where $\mathbf{X}:=x_{1}+x_{2}+\cdots \in \Lambda_{q, t}$. Using another plethystic substitution, we define the $E H A$ superpolynomial

$$
\begin{equation*}
\mathcal{P}_{C}^{\mathcal{E}}(a, q, t):=F_{C}\left[a-a^{-1}\right] . \tag{1.11}
\end{equation*}
$$

In the notation of Theorem 1.7, we therefore get

$$
\begin{equation*}
F_{C_{+}}=q t F_{C_{-}}+F_{C_{0}} \quad \text { and } \quad \mathcal{P}_{C_{+}}^{\mathcal{E}}=q t \mathcal{P}_{C_{-}}^{\mathcal{E}}+\mathcal{P}_{C_{0}}^{\mathcal{E}} . \tag{1.12}
\end{equation*}
$$



Figure 4. Examples of monotone curves. See also Table 1 .
As explained in Remark 3.4, the symmetric function $F_{C}$ is $q$, $t$-symmetric (i.e., unchanged under swapping $q$ and $t$ ).

Note that 1.8) does not extend to symmetric functions: for $C=\left[C_{1} C_{2} \ldots C_{k}\right]$, knowing the symmetric functions $D_{C_{1}} \cdot 1, D_{C_{2}} \cdot 1, \ldots, D_{C_{k}} \cdot 1$ does not allow one to reconstruct

$$
D_{C} \cdot 1=D_{C_{1}} \cdot\left(D_{C_{2}} \cdot\left(\cdots D_{C_{k}} \cdot 1 \cdots\right)\right)
$$

1.7. Convex curves. The following class of curves is motivated by our results on cohomology of open positroid varieties [GL20, GL21].
Definition 1.11. We say that a curve $C$ is convex if it is a plot of a (weakly) convex function $f:[0, m] \rightarrow[0, n]$.

We also consider the following slightly more general class of curves.
Definition 1.12. A set $A \subset \mathbb{R}^{2}$ is called $\mathbb{Z}$-convex if $\operatorname{Conv}(A) \cap \mathbb{Z}^{2}=A \cap \mathbb{Z}^{2}$. For a curve $C$ passing through lattice points $(0,0)=\boldsymbol{p}_{0}, \boldsymbol{p}_{1}, \ldots, \boldsymbol{p}_{k}=(m, n)$, let $A_{C}$ be the set of all lattice points in $[0, m] \times[0, n]$ strictly above $C$ together with the set of (non-lattice) points $\left\{\boldsymbol{p}_{i}+(-\epsilon, \epsilon) \mid i=0,1, \ldots, k\right\}$, where $\epsilon>0$ is small. We say that $C$ is $\mathbb{Z}$-convex if $A_{C}$ is a $\mathbb{Z}$-convex set.

For example, the curves in Figure $4(\mathrm{a}, \mathrm{b}, \mathrm{d})$ are $\mathbb{Z}$-convex while the curves in Figure $4(\mathrm{c}, \mathrm{e})$ are not.

It is clear that any convex curve is $\mathbb{Z}$-convex, but the converse need not hold. For instance, an almost linear curve (Definition 1.8 from $(0,0)$ to $(m, n)$ is always $\mathbb{Z}$-convex but it is convex only if $\operatorname{gcd}(m, n)=1$. It is not hard to check that a piecewise almost linear curve $C=\left[C_{1} C_{2} \ldots C_{k}\right]$, where each $C_{i}$ is $\left(m_{i}, n_{i}\right)$-almost linear, is $\mathbb{Z}$-convex if and only if

$$
\begin{equation*}
\frac{m_{1}}{n_{1}} \geq \frac{m_{2}}{n_{2}} \geq \cdots \geq \frac{m_{k}}{n_{k}} \tag{1.13}
\end{equation*}
$$

The following conjecture extends $\left[\mathrm{BHM}^{+} 21\right.$, Conjecture 7.1.1] in view of Remark 7.9 .
Conjecture 1.13. For $a \mathbb{Z}$-convex curve $C$, the formal power series

$$
\begin{equation*}
\frac{1}{(1-t)^{\mathrm{k}(C)-1}} F_{C} \tag{1.14}
\end{equation*}
$$

is $q, t$-Schur positive.
Here $\frac{1}{1-t}=1+t+t^{2}+\cdots$ is viewed as a formal power series. See Example 1.15. Section 1.9. Figure 4, and Table 1 for examples.

Remark 1.14. In fact, computational evidence (see Example 1.15) suggests that the class of $\mathbb{Z}$-convex curves can be slightly enlarged, as follows. In the notation of Definition 1.12 , let $A_{C}^{\prime}$ be the set of all lattice points in $[0, m] \times[0, n]$ strictly above $C$ together with $\left\{\boldsymbol{p}_{0}+\right.$ $\left.(-\epsilon, \epsilon), \boldsymbol{p}_{k}+(-\epsilon, \epsilon)\right\}$. We say that $C$ is weakly $\mathbb{Z}$-convex if $A_{C}^{\prime}$ is $\mathbb{Z}$-convex. We conjecture that the formal power series 1.14 is Schur positive for all weakly $\mathbb{Z}$-convex curves.

Example 1.15. For $1 \leq m, n \leq 7$, there are 24,319 monotone curves. Among them:
(1) $6,781(27 \%)$ have Schur positive formal power series (1.14);
(2) $4,257(17 \%)$ are weakly $\mathbb{Z}$-convex;
(3) 3, $313(13 \%)$ are $\mathbb{Z}$-convex;
and we have inclusions $(1) \supset(2) \supset(3)$.
Remark 1.16. Let $C$ be a straight line segment from $(0,0)$ to $(m, n)$. Then $L_{C}$ is the ( $m, n$ )-torus link. If $\operatorname{gcd}(m, n)=1$, then $L_{C}$ has a single component, and is the ( $m, n$ )-torus knot. If instead $C$ is the almost linear curve from $(0,0)$ to $(m, n)$ then $L_{C}$ is a knot which we call the $(m, n)$-almost torus knot. This knot is algebraic and corresponds to a plane curve singularity with Puiseaux exponents $(n, m, m+1)$ studied in [Pio07, GMO22]; see Section 8 for further discussion.

The following class includes the coaxial torus links considered in [EN85, Section 17b)].
Definition 1.17. When $C$ is a piecewise almost linear curve, we call $L_{C}$ a coaxial almost torus link. If $C$ is in addition $\mathbb{Z}$-convex, then $L_{C}$ is called a $\mathbb{Z}$-convex coaxial almost torus link.

Recall that an algebraic link is an intersection of a small 3 -sphere (inside $\mathbb{C}^{2} \cong \mathbb{R}^{4}$ ) with the zero set $\left\{(x, y) \in \mathbb{C}^{2} \mid f(x, y)=0\right\}$ of solutions to a polynomial equation. We prove the following in Section 8 .

Proposition 1.18. $\mathbb{Z}$-convex coaxial almost torus links are algebraic.
In Corollary 4.3, we give an explicit formula expressing the element $D_{C}$ for an arbitrary $\mathbb{Z}$-convex curve $C$ in terms of $\mathbb{Z}$-convex piecewise almost linear curves. In particular, the invariants we associate to $\mathbb{Z}$-convex links are expressed (with predictable alternating signs) in terms of invariants of algebraic links. We do not have an analog of this result where " $\mathbb{Z}$-convex" is replaced with "weakly $\mathbb{Z}$-convex." See Figure $4(\mathrm{e})$.
1.8. Khovanov-Rozansky homology. To a link $L$, one can associate a link invariant $\mathcal{P}^{\mathrm{KR}}(L ; a, q, t)$ which is a Laurent polynomial in $a, q^{1 / 2}, t^{1 / 2}$ encoding the graded dimensions of Khovanov-Rozansky (KR) homology of $L$; see KR08a, KR08b, Kho07] ${ }^{2}$ When the odd KR homology of $L$ vanishes, $\mathcal{P}^{\mathrm{KR}}(L ; a, q, t)$ becomes a Laurent polynomial in $a, q, t$ (involving no half-integer powers of $q, t)$.

It is well known that at $t=q^{-1}$ (more precisely, at $\left.t^{1 / 2}=-q^{-1 / 2}\right), \mathcal{P}^{\mathrm{KR}}(L ; a, q, t)$ specializes to the HOMFLY polynomial $\mathcal{P}_{L}^{\mathrm{HOMFLY}}(a, q)$ of $L$. We show that the same holds for the superpolynomial $\mathcal{P}_{C}^{\mathcal{E}}(a, q, t)$ defined in (1.11).
Proposition 1.19. For any curve $C$, we have

$$
\begin{equation*}
\delta_{q, q^{-1}}^{\mathrm{k}(C)} \cdot \mathcal{P}_{C}^{\mathcal{E}}\left(a, q, t=q^{-1}\right)=a^{\mathrm{w}(C)} \cdot \mathcal{P}_{L_{C}}^{\mathrm{HOMFLY}}(a, q), \tag{1.15}
\end{equation*}
$$

[^2]where $\mathrm{w}(C) \in \mathbb{Z}$ is the writhe of the braid $\beta_{C}^{\mathbb{A}}$ associated to $C$ in Definition 6.5 .
An explicit formula for $\mathrm{w}(C)$ in terms of lattice points below $C$ is given in (6.9). Here $\mathcal{P}_{L}^{\text {HOMFLY }}(a, q)$ has slightly non-standard normalization; see (5.2).

A natural question arises: what is the relationship between $\mathcal{P}_{C}^{\mathcal{E}}(a, q, t)$ and $\mathcal{P}_{L_{C}}^{\mathrm{KR}}(a, q, t)$ ? For arbitrary curves, it is easy to find examples where these two polynomials disagree: see Figure 4(c) and Example A.2. However, the two polynomials appear to be very closely related for the class of $\mathbb{Z}$-convex curves. The following question has motivated most of our results.

Question 1.20. For which $\mathbb{Z}$-convex curves $C$ do we have

$$
\begin{equation*}
\mathcal{P}_{C}^{\mathcal{E}}(a, q, t)=(1-t)^{\mathrm{k}(C)-1} \mathcal{P}_{L_{C}}^{\mathrm{KR}}(a, q, t) \tag{1.16}
\end{equation*}
$$

(up to multiplication by an explicit monomial in a, $q^{1 / 2}, t^{1 / 2}$ )?
Note that if $(1.16)$ holds for $C$ then the odd KR homology of $L_{C}$ vanishes. We refer to Example A. 3 for an example of a convex curve $C$ (discovered by A. Mellit and brought to our attention by M. Mazin) for which (1.16) does not hold. In particular, this example disproves [GL21, Conjecture 7.1(ii,iv)].
Remark 1.21. It was shown in [HM19, Corollary 1.4] (see also [Mel16, EH19, Mel22]) that torus links have vanishing odd KR homology. Recall from Remark 1.16 that torus links are special cases of links $L_{C}$ when $C$ is a straight line segment from $(0,0)$ to $(m, n)$. It would be interesting to verify directly using the results of [HM19] that (1.16) holds for torus links. This case is also covered by the conjectures of Cherednik-Danilenko [CD17.
Remark 1.22. It would be interesting to interpret the skein relation (1.9) in terms of KR homology. We note the similarity to the results of Gorsky and Negut (for example [GN22, Theorem 5.3]) on traces in the affine Hecke category, which is related to annular, or affine KR homology. See also Remark 5.12,
Conjecture 1.23. Equation 1.16) holds for convex curves $C$ such that the link $L_{C}$ is algebraic.
1.9. An example. Let $(m, n)=(2,2)$, and consider the convex curves $C_{+}, C_{-}, C_{0}$ shown in Figure 3; see also Figure 12. Thus, $L_{+}:=L_{C_{+}}$is the (positive) trefoil knot, $L_{-}:=L_{C_{-}}$is the unknot, and $L_{0}:=L_{C_{0}}$ is the (positive) Hopf link. The associated symmetric functions $F_{C}$ and normalized EHA superpolynomials $\widehat{\mathcal{P}}_{C}^{\mathcal{E}}(a, q, t):=\mathcal{P}_{C}^{\mathcal{E}}(a, q, t) /\left(a-a^{-1}\right)$ are given by

$$
\begin{array}{lll}
F_{C_{+}}=s_{11}+(q+t) s_{2}, & F_{C_{-}}=s_{2}, & F_{C_{0}}=s_{11}+(q+t-q t) s_{2} \\
\widehat{\mathcal{P}}_{C_{+}}^{\mathcal{E}}=a^{3} \cdot\left(\frac{q+t}{a^{2}}-\frac{1}{a^{4}}\right), & \widehat{\mathcal{P}}_{C_{-}}^{\mathcal{E}}=a^{1} \cdot 1, & \widehat{\mathcal{P}}_{C_{0}}^{\mathcal{E}}=a^{3} \cdot\left(\frac{q+t-q t}{a^{2}}-\frac{1}{a^{4}}\right) . \tag{1.18}
\end{array}
$$

(See Example 4.2 for the full computation.) We see that the skein relation (1.12) holds in this case. All of the above expressions are $q, t$-symmetric. In addition, $F_{C_{+}}, F_{C_{-}}$are $q, t$-Schur positive, and so is

$$
\frac{1}{1-t} F_{C_{0}}=\left(1+t+t^{2}+t^{3}+\cdots\right) s_{11}+\left(q+t+t^{2}+t^{3}+\cdots\right) s_{2}
$$

in agreement with Conjecture 1.13. Finally, computing KR homology of $L_{+}, L_{-}, L_{0}$ (see e.g. [HM19, Theorem 1.2], Mel22, Section 1.2], or GL20, Section 3.5]), one checks that indeed the odd KR homology of $L_{+}, L_{-}$, and $L_{0}$ vanishes, and (1.16) holds for these links. We have $\mathrm{w}\left(C_{+}\right)=3, \mathrm{w}\left(C_{-}\right)=1, \mathrm{w}\left(C_{0}\right)=3$, in agreement with (1.15).
1.10. Comparisons and specializations. Various special cases of our operators $D_{C}$ have appeared before in the literature, and we list some comparisons in Section 7. The operator $D_{C}$ simplifies considerably when $t=1$, and we show in Proposition 7.12 that

$$
\left.F_{C}\right|_{t=1}=\sum_{\mathcal{P}} q^{\operatorname{area}\left(\mathcal{P}_{C}\right)-\operatorname{area}(\mathcal{P})} h_{\mathcal{P}}
$$

summed over lattice paths $\mathcal{P}$ weakly below $C$, such that $\mathcal{P}$ passes through all the lattice points that $C$ passes through. Here, $h_{\mathcal{P}}$ denotes a complete homogeneous symmetric function and $\operatorname{area}\left(\mathcal{P}_{C}\right)-\operatorname{area}(\mathcal{P})$ is a statistic on lattice paths to be defined in Section 7 .
1.11. Structure of the paper. We give background on DAHA and EHA in Sections 2 and 3, respectively. Along the way, we analyze the operators $D_{C}^{(N)}$ associated to almost linear curves. In Section 4, we prove the skein relation (Theorem 1.7) and use it to prove Theorem 1.6. We also give a non-recursive formula (Corollary 4.3) expressing an arbitrary $\mathbb{Z}$-convex curve in terms of $\mathbb{Z}$-convex piecewise almost linear curves. In Section 5, we discuss the skein-theoretic formalism of MS17, MS21 and prove Theorem 1.5. In Section 6, we describe the maps in the diagram in Figure1, the image of a curve $C$ under these maps, and check that the diagram commutes. In Section 7, we explain how our objects are related to the objects studied in BHM $^{+}$21, BGLX15, Neg14, GL21, OR17. In particular, we identify monotone links in an annulus with Coxeter links in Proposition 7.5 and discuss the $t=1$ specialization of our results in Section 7.6. In Section 8, we review the results of [EN85] on algebraic links and prove Proposition 1.18. Finally, we list some examples in Appendix A.

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## 2. From curves to DAHA

In this section, we review the background on the DAHA and associate an element $D_{C}^{(N)} \in$ SḦ $\ddot{H}_{N ; q, t}$ in the spherical DAHA to a monotone curve $C$.
2.1. Double affine Hecke algebra. Let $N \geq 1$. The double affine Hecke algebra (DAHA) introduced by Cherednik Che05] is the $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)$-algebra generated by $X_{i}^{ \pm 1}, Y_{i}^{ \pm 1}$ for $i=$ $1,2, \ldots, N$, and $T_{i}$ for $i=1,2, \ldots, N-1$ subject to the following relations:

$$
\begin{gather*}
\left(T_{i}+t^{1 / 2}\right)\left(T_{i}-t^{-1 / 2}\right)=0, \quad T_{i} T_{i+1} T_{i}=T_{i+1} T_{i} T_{i+1},  \tag{2.1}\\
T_{i} T_{k}=T_{k} T_{i} \quad \text { if }|i-k|>1,  \tag{2.2}\\
X_{j} X_{k}=X_{k} X_{j} \quad \text { and } \quad Y_{j} Y_{k}=Y_{k} Y_{j} \quad \text { for all } 1 \leq j, k \leq N,  \tag{2.3}\\
T_{i} X_{i} T_{i}=X_{i+1}, \quad T_{i}^{-1} Y_{i} T_{i}^{-1}=Y_{i+1},  \tag{2.4}\\
T_{i} X_{k}=X_{k} T_{i} \quad \text { and } T_{i} Y_{k}=Y_{k} T_{i} \quad \text { if }|i-k|>1,  \tag{2.5}\\
Y_{1} X_{1} X_{2} \cdots X_{N}=q X_{1} X_{2} \cdots X_{N} Y_{1},  \tag{2.6}\\
X_{1}^{-1} Y_{2}=Y_{2} X_{1}^{-1} T_{1}^{-2} \tag{2.7}
\end{gather*}
$$

Notation 2.1. In the above relations, we follow the conventions of [SV11, MS21, which differ from those of [Che05, GN15] by substituting $t^{1 / 2} \mapsto t^{-1 / 2}$.

Notation 2.2. Following [MS21] (cf. Notation 5.9), we represent each $T_{i}$ by a negative crossing $\lambda^{\top}$ in our figures. Thus, (2.1) is consistent with (1.1).

Let $\mathfrak{S}_{N}$ denote the symmetric group on $N$ letters. For a permutation $w \in \mathfrak{S}_{N}$, let $\ell(w)$ be the number of inversions in $w$. Given a reduced word $w=s_{i_{1}} s_{i_{2}} \cdots s_{i_{\ell(w)}}$, where $s_{i}=(i, i+1)$ are simple transpositions, we let $T_{w}:=T_{i_{1}} T_{i_{2}} \cdots T_{i_{\ell(w)}}$; the result depends only on $w$.

The symmetrizing idempotent is given by

$$
\begin{equation*}
\boldsymbol{e}_{N}:=\frac{\sum_{w \in \mathfrak{S}_{N}} t^{-\ell(w) / 2} T_{w}}{\sum_{w \in \mathfrak{S}_{N}} t^{-\ell(w)}} \tag{2.8}
\end{equation*}
$$

The symmetrizer $\boldsymbol{e}_{N}$ satisfies

$$
\begin{equation*}
T_{i} \boldsymbol{e}_{N}=\boldsymbol{e}_{N} T_{i}=t^{-1 / 2} \boldsymbol{e}_{N} \quad \text { and } \quad \boldsymbol{e}_{N}^{2}=\boldsymbol{e}_{N} . \tag{2.9}
\end{equation*}
$$

The spherical DAHA is defined by

$$
\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}:=\boldsymbol{e}_{N} \ddot{\mathbf{H}}_{N ; q, t} \boldsymbol{e}_{N} .
$$

For $1 \leq i \leq j \leq N$, let $\mathfrak{S}_{[i, j]}:=\left\{w \in \mathfrak{S}_{N} \mid w(k)=k\right.$ for $k<i$ or $\left.k>j\right\}$, and set

$$
\begin{equation*}
\boldsymbol{e}_{[i, j]}:=\frac{\sum_{w \in \mathfrak{S}_{[i, j]}} t^{-\ell(w) / 2} T_{w}}{\sum_{w \in \mathfrak{G}_{[i, j]}} t^{-\ell(w)}} \tag{2.10}
\end{equation*}
$$

Thus, $\boldsymbol{e}_{[1, N]}=\boldsymbol{e}_{N}$. The partial symmetrizers $\boldsymbol{e}_{[k, N]}$ satisfy (2.9) for all $i=k, k+1, \ldots, N-1$, and can be computed inductively using the following well-known recurrence (see e.g. EH19, Section 1.2] and Remark 5.12):

$$
\begin{equation*}
\boldsymbol{e}_{[k+1, N]} T_{k} \cdots T_{N-1} T_{N-1} \cdots T_{k}=-t\left(1-t^{-N-1+k}\right) \boldsymbol{e}_{[k, N]}+t \boldsymbol{e}_{[k+1, N]}, \quad \boldsymbol{e}_{[N, N]}=1 \tag{2.11}
\end{equation*}
$$

2.2. Polynomial representation and $\mathrm{SL}_{2}(\mathbb{Z})$-action. The DAHA $\ddot{\mathbf{H}}_{N ; q, t}$ admits a polynomial representation $\phi_{N}$ on $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)\left[x_{1}, \ldots, x_{N}\right]$. For a polynomial $f\left(x_{1}, \ldots, x_{N}\right)$, set

$$
\begin{aligned}
(\rho \cdot f)\left(x_{1}, \ldots, x_{N-1}, x_{N}\right) & :=f\left(q x_{N}, x_{1}, \ldots, x_{N-1}\right), \\
\left(s_{i} \cdot f\right)\left(\ldots, x_{i}, x_{i+1}, \ldots\right) & :=f\left(\ldots, x_{i+1}, x_{i}, \ldots\right) .
\end{aligned}
$$

The operator $\phi_{N}\left(X_{i}\right)$ acts by multiplication by $q^{-1} x_{i}$, and $T_{i}, Y_{i}$ correspond to the following operators; cf. [SV11, Lemma 4.2]:

$$
\begin{align*}
& \phi_{N}\left(T_{i}\right)=t^{-1 / 2} s_{i}+\frac{t^{-1 / 2}-t^{1 / 2}}{x_{i} / x_{i+1}-1}\left(s_{i}-1\right)  \tag{2.12}\\
& \phi_{N}\left(Y_{i}\right)=t^{(N-1) / 2} \phi_{N}\left(T_{i} \cdots T_{N-1}\right) \rho \phi_{N}\left(T_{1}^{-1} \cdots T_{i-1}^{-1}\right) \tag{2.13}
\end{align*}
$$

Notation 2.3. We usually omit $\phi_{N}$ from the notation and write $D \cdot f$ in place of $\phi_{N}(D) \cdot f$ for $D \in \ddot{\mathbf{H}}_{N ; q, t}$ and $f \in \mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)\left[x_{1}, \ldots, x_{N}\right]$.

Remark 2.4. Let $\phi_{N}^{\prime}$ be the representation defined in SV11, Lemma 4.2] and [SV13, Section 1.4]. Then we have $\phi_{N}\left(T_{i}\right)=\phi_{N}^{\prime}\left(T_{i}\right), \phi_{N}\left(X_{i}\right)=q^{-1} \phi_{N}^{\prime}\left(X_{i}\right)$, and $\phi_{N}\left(Y_{i}\right)=t^{(N-1) / 2} \phi_{N}^{\prime}\left(Y_{i}\right)$.

This rescaling is consistent ${ }^{3}$ with the rescaling $P_{i, j}^{N} \mapsto y_{1}^{i} y_{2}^{j} P_{i, j}^{N}$ in [SV13, Equation (1.12)], with $y_{1}=q^{-1}$ and $y_{2}=t^{(N-1) / 2}$.

Consider the braid group $\mathcal{B}_{3}$ with generators $\tau_{+}, \tau_{-}$and relations $\tau_{+} \tau_{-}^{-1} \tau_{+}=\tau_{-}^{-1} \tau_{+} \tau_{-}^{-1}$. We have an action of $\mathcal{B}_{3}$ by automorphisms on $\ddot{\mathbf{H}}_{N ; q, t}$ defined by ${ }^{4}$

$$
\begin{array}{lcc}
\tau_{+}\left(T_{i}\right)=T_{i}, & \tau_{+}\left(X_{i}\right)=X_{i}, & \tau_{+}\left(Y_{i}\right)=Y_{i} X_{i}\left(T_{i-1}^{-1} \cdots T_{1}^{-1}\right)\left(T_{1}^{-1} \cdots T_{i-1}^{-1}\right) ; \\
\tau_{-}\left(T_{i}\right)=T_{i}, & \tau_{-}\left(Y_{i}\right)=Y_{i}, & \tau_{-}\left(X_{i}\right)=X_{i} Y_{i}\left(T_{i-1} \cdots T_{1}\right)\left(T_{1} \cdots T_{i-1}\right) \tag{2.15}
\end{array}
$$

In particular,
$\tau_{+}\left(X_{1}\right)=X_{1}, \quad \tau_{+}\left(Y_{1}\right)=Y_{1} X_{1}, \quad \tau_{-}\left(X_{1}\right)=X_{1} Y_{1}, \quad \tau_{-}\left(Y_{1}\right)=Y_{1}, \quad \tau_{+}\left(\boldsymbol{e}_{N}\right)=\tau_{-}\left(\boldsymbol{e}_{N}\right)=\boldsymbol{e}_{N}$.
The operators $\tau_{+}, \tau_{-}$preserve $\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$, and under the identification

$$
\tau_{+} \mapsto\left(\begin{array}{ll}
1 & 1  \tag{2.16}\\
0 & 1
\end{array}\right), \quad \tau_{-} \mapsto\left(\begin{array}{ll}
1 & 0 \\
1 & 1
\end{array}\right)
$$

we obtain an action of $\mathrm{SL}_{2}(\mathbb{Z})$ on $\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$. See e.g. MS21, Proposition 5.2] for an explicit check of the $\mathrm{SL}_{2}(\mathbb{Z})$ relation $\left(\tau_{+} \tau_{-}^{-1} \tau_{+}\right)^{4}=\mathrm{id} ل^{5}$

For any polynomial $f\left(x_{1}, \ldots, x_{N}\right)$, the polynomial $\boldsymbol{e}_{N} \cdot f$ is symmetric in $x_{1}, \ldots, x_{N}$. Thus, the polynomial representation of $\ddot{\mathbf{H}}_{N ; q, t}$ restricts to an action of $\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$ on the space of $\Lambda_{N ; q, t}$ of symmetric polynomials in $N$ variables over $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)$.

We denote

$$
\begin{gathered}
\mathbb{Z}^{\geq}:=\{x \in \mathbb{Z} \mid x \geq 0\}, \quad \mathbb{Z}^{>}:=\{x \in \mathbb{Z} \mid x>0\}, \quad \text { and } \\
\mathbf{Z}:=\mathbb{Z}^{2}, \quad \mathbf{Z}^{*}:=\mathbf{Z} \backslash\{(0,0)\}, \quad \mathbf{Z}^{\geq}:=\mathbb{Z}^{\geq} \times \mathbb{Z}, \quad \mathbf{Z}^{>}:=\mathbb{Z}^{>} \times \mathbb{Z}, \quad \mathbf{Z}^{+}:=\mathbf{Z}^{>} \sqcup\left(\{0\} \times \mathbb{Z}^{\geq}\right) .
\end{gathered}
$$

For $d \geq 1$, let

$$
\begin{equation*}
P_{d, 0}^{(N)}:=q^{d} \boldsymbol{e}_{N} \sum_{i=1}^{N} X_{i}^{d} \boldsymbol{e}_{N} \quad \text { and } \quad P_{0, d}^{(N)}:=\boldsymbol{e}_{N} \sum_{i=1}^{N} Y_{i}^{d} \boldsymbol{e}_{N} . \tag{2.17}
\end{equation*}
$$

For an arbitrary vector $(m, n) \in \mathbf{Z}^{*}$ with $\operatorname{gcd}(m, n)=d$, choose an element $g \in \operatorname{SL}_{2}(\mathbb{Z})$ sending $(d, 0)$ to $(m, n)$ and set

$$
\begin{equation*}
P_{m, n}^{(N)}:=g P_{d, 0}^{(N)} . \tag{2.18}
\end{equation*}
$$

The resulting element does not depend on the particular choice of $g$. By SV11, Proposition 2.5], the elements $P_{\boldsymbol{x}}^{(N)}, \boldsymbol{x} \in \mathbf{Z}^{*}$ generate $\mathbf{S} \ddot{H}_{N ; q, t}$ as a $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)$-algebra.

[^3]

Figure 5. The action of $\tau_{+}, \tau_{-}$on $\pi_{1}\left(\mathbb{T}_{\boldsymbol{r}}^{*}, 0\right)$ agrees with the action (2.14) 2.15) on $\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$. See Lemma 2.5.
2.3. Comparing two $\mathrm{SL}_{2}(\mathbb{Z})$-actions. The group $\mathrm{SL}_{2}(\mathbb{Z})$ acts on $\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$, and it also acts linearly on $\mathbb{R}^{2}$ (and thus on curves in $\mathbb{R}^{2}$ ). The goal of this section is to show that these two actions are compatible with Definition 1.3; see Corollary 2.6.

Choose a nonzero vector $\boldsymbol{r} \in \mathbb{R}_{\geq 0}^{2} \backslash\{0\}$. Consider the $\boldsymbol{r}$-punctured torus $\mathbb{T}_{\boldsymbol{r}}^{*}:=\mathbb{T} \backslash\{\epsilon \boldsymbol{r}\}$ for some small $\epsilon>0$. In other words, $\mathbb{T}_{\boldsymbol{r}}^{*}=\mathbb{R}_{r}^{2, *} / \mathbb{Z}^{2}$, where $\mathbb{R}_{\boldsymbol{r}}^{2, *}=\mathbb{R}^{2} \backslash\{\boldsymbol{p}+\epsilon \boldsymbol{r} \mid \boldsymbol{p} \in \mathbf{Z}\}$. Since $\mathbb{T}_{\boldsymbol{r}}^{*}$ is homotopy equivalent to a wedge of two circles, its fundamental group $\pi_{1}\left(\mathbb{T}_{\boldsymbol{r}}^{*}, 0\right)$ (with loops based at $0 \in \mathbb{T}_{r}^{*}$ ) is the free product $\mathbb{Z} * \mathbb{Z}$. We choose two particular generators $X_{r}, Y_{r} \in \pi_{1}\left(\mathbb{T}_{\boldsymbol{r}}^{*}, 0\right)$ such that the loop representing $X_{r}$ (resp., $Y_{\boldsymbol{r}}$ ) lifts to a path in $\mathbb{R}_{\boldsymbol{r}}^{2, *}$ from $(0,0)$ to $(1,0)$ (resp., from $(0,0)$ to $(0,1))$ passing below (resp., to the left of) the point $\epsilon \boldsymbol{r}$ as shown in Figure $5($ middle $)$, Since $\pi_{1}\left(\mathbb{T}_{r}^{*}, 0\right)$ is freely generated by $X_{r}, Y_{r}$, we can define a group homomorphism

$$
\psi_{\boldsymbol{r}}^{(N)}: \pi_{1}\left(\mathbb{T}_{\boldsymbol{r}}^{*}, 0\right) \rightarrow \ddot{\mathbf{H}}_{N ; q, t}^{\times}: \quad X_{\boldsymbol{r}} \mapsto X_{1}, \quad Y_{\boldsymbol{r}} \mapsto Y_{1}
$$

Let $C:[0,1] \rightarrow \mathbb{R}_{r}^{2, *}$ be an arbitrary curve with $C(0), C(1) \in \mathbb{Z}^{2}$. Applying the projection $\mathbb{R}^{2} \rightarrow \mathbb{T}$, we get a curve $\bar{C}:[0,1] \rightarrow \mathbb{T}_{r}^{*}$ with $C(0)=C(1)=0$, which therefore represents an element of $\pi_{1}\left(\mathbb{T}_{r}^{*}, 0\right)$, also denoted $\bar{C}$. We will be interested in the element $\psi_{r}^{(N)}(\bar{C}) \in \ddot{\mathbf{H}}_{N ; q, t}$.

We have a homomorphism $\mathcal{B}_{3} \rightarrow \mathrm{SL}_{2}(\mathbb{Z})$ defined by (2.16). Let $\mathcal{B}_{3}^{+} \subset \mathcal{B}_{3}$ be the monoid generated by $\tau_{+}, \tau_{-}$. In the following lemma, $g \in \mathcal{B}_{3}^{+}$is simultaneously treated as an automorphism of $\ddot{\mathbf{H}}_{N ; q, t}$ as well as a linear map $\mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ (induced by the image of $g$ in $\mathrm{SL}_{2}(\mathbb{Z})$ which we also denote by $g$ ).

Lemma 2.5. Suppose that $g \in \mathcal{B}_{3}^{+}$, and let $C:[0,1] \rightarrow \mathbb{R}_{r}^{2, *}$ be a curve with $C(0), C(1) \in \mathbb{Z}^{2}$. Let $\boldsymbol{r}^{\prime}:=g(\boldsymbol{r}) \in \mathbb{R}_{\geq 0}^{2} \backslash\{0\}$ and $C^{\prime}:=g \circ C:[0,1] \rightarrow \mathbb{R}_{\boldsymbol{r}^{\prime}}^{2, *}$. Then the action of $g$ on $\ddot{\mathbf{H}}_{N ; q, t}$ sends $\psi_{\boldsymbol{r}}^{(N)}(\bar{C})$ to $\psi_{r^{\prime}}^{(N)}\left(\overline{C^{\prime}}\right)$.

Proof. The linear map $g: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ restricts to a homeomorphism $\mathbb{R}_{r}^{2, *} \xrightarrow{\sim} \mathbb{R}_{r^{\prime}}^{2, *}$ and to a bijection $\mathbb{Z}^{2} \xrightarrow{\sim} \mathbb{Z}^{2}$. Therefore composition with $g$ gives rise to a group isomorphism $g_{*}: \pi_{1}\left(\mathbb{T}_{r}^{*}, 0\right) \xrightarrow{\sim} \pi_{1}\left(\mathbb{T}_{r^{\prime}}^{*}, 0\right)$. Our goal is to show that the group homomorphism $\psi_{\boldsymbol{r}}^{(N)}$ coincides with $\psi_{\boldsymbol{r}^{\prime}}^{(N)} \circ g_{*}$.

It suffices to consider the cases $g=\tau_{+}, \tau_{-}$, and only to check the equality $\psi_{r}^{(N)}(Z)=$ $\psi_{r^{\prime}}^{(N)}\left(g_{*}(Z)\right)$ when $Z=X_{r}, Y_{r}$ is a generator of $\pi_{1}\left(\mathbb{T}_{r}^{*}, 0\right)$. This is done in Figure 5 .

Let $C=\left[C_{1} C_{2} \cdots C_{k}\right]$ be a curve from $(0,0)$ to $(m, n) \in\left(\mathbb{Z}^{>}\right)^{2}$. Choosing $\boldsymbol{r}:=(1,0)$ and $\epsilon>0$ small enough, we see that whenever $C$ passes through a lattice point $\boldsymbol{p} \neq(m, n)$, it passes above the point $\boldsymbol{p}+\epsilon \boldsymbol{r}$. Thus, we find that the element $D_{C}^{(N)}$ constructed in Definition 1.3 is given by

$$
D_{C}^{(N)}=\gamma_{N ; t} \boldsymbol{e}_{N} \cdot \psi_{\boldsymbol{r}}^{(N)}\left(\bar{C}_{1}\right) \cdot \gamma_{N ; t} \boldsymbol{e}_{N} \cdot \psi_{\boldsymbol{r}}^{(N)}\left(\bar{C}_{2}\right) \cdots \gamma_{N ; t} \boldsymbol{e}_{N} \cdot \psi_{\boldsymbol{r}}^{(N)}\left(\bar{C}_{k}\right) \cdot \boldsymbol{e}_{N} .
$$

Since the maps $\tau_{+}, \tau_{-}$send monotone curves to monotone curves and $\boldsymbol{e}_{N}$ to $\boldsymbol{e}_{N}$, Lemma 2.5 implies the following result.

Corollary 2.6. If $g \in \mathcal{B}_{3}^{+}$, then for any curve $C$, we have

$$
g\left(D_{C}^{(N)}\right)=D_{g(C)}^{(N)} .
$$

2.4. Almost linear elements. For an almost linear curve $C$ from ( 0,0 ) to ( $m, n$ ) (cf. Definition 1.8), denote

$$
D_{m, n}^{(N)}:=D_{C}^{(N)}
$$

A natural question arises: how is $D_{m, n}^{(N)}$ expressed in the generators $P_{\boldsymbol{x}}^{(N)}$ of $\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$ defined in 2.18)? The goal of this subsection is to prove the following result.
Theorem 2.7. For all $m, n, N \geq 1$, the element $D_{m, n}^{(N)}$ is expressed as a $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)$-linear combination of products of generators $P_{\boldsymbol{x}}^{(N)}$ with coefficients that do not depend on $N$.

The above coefficients are expressed in the language of symmetric functions; see [Sta99] for background and notation.

First, we would like to understand the relationship between the elements $D_{m, n}^{(N)} \in \mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$ and the $\mathrm{SL}_{2}(\mathbb{Z})$-action. For $d \geq 1$, define

$$
\begin{equation*}
D_{d, 0}^{(N)}:=\gamma_{N ; t} \boldsymbol{e}_{N} \cdot Y_{1} X_{1}^{d} Y_{1}^{-1} \cdot \boldsymbol{e}_{N} \tag{2.19}
\end{equation*}
$$

Lemma 2.8. Let $m, n \geq 1$ and $d:=\operatorname{gcd}(m, n)$. Then there exists $g \in \mathcal{B}_{3}^{+}$such that the corresponding element of $\mathrm{SL}_{2}(\mathbb{Z})$ sends $(d, 0)$ to $(m, n)$. For any such $g$, we have

$$
\begin{equation*}
g D_{d, 0}^{(N)}=D_{m, n}^{(N)} . \tag{2.20}
\end{equation*}
$$

Proof. First, it is well known (Euclid's algorithm) that the monoid $\mathcal{B}_{3}^{+}$contains an element $g$ sending $(d, 0)$ to $(m, n)$. Let $g \in \mathcal{B}_{3}^{+}$be any such element.

Let $C_{d, 0}$ be a curve from $(0,0)$ to $(d, 0)$ proceeding monotonously from left to right slightly above the $x$ axis. We extend Definition 1.3 to $C_{d, 0}$, with the lattice path $\mathcal{P}_{C_{d, 0}}$ consisting of $d$ right steps. The resulting element $D_{C_{d, 0}}^{(N)}$ coincides with the element $D_{d, 0}^{(N)}$ given by 2.19 . The result now follows from Corollary 2.6.

Let $\mathbf{X}_{N}:=x_{1}+\cdots+x_{N}$. We start by computing the action of $D_{d, 0}^{(N)}$ on $1 \in \Lambda_{q, t}$.
Proposition 2.9. For $d, N \geq 1$, we have

$$
\begin{equation*}
D_{d, 0}^{(N)} \cdot 1=(-t)^{d} e_{d}\left[\left(1-t^{-1}\right) \mathbf{X}_{N}\right] \tag{2.21}
\end{equation*}
$$

Here $e_{d} \in \Lambda_{q, t}$ denotes the $d$-th elementary symmetric function, and the square brackets denote plethystic substitution; see Section 7 .

Proof. We have
$D_{d, 0}^{(N)} \cdot 1=\gamma_{N ; t} \boldsymbol{e}_{N} Y_{1} X_{1}^{d} Y_{1}^{-1} \boldsymbol{e}_{N} \cdot 1=\gamma_{N ; t} \boldsymbol{e}_{N} Y_{1} X_{1}^{d} Y_{1}^{-1} \cdot 1=\gamma_{N ; t} \boldsymbol{e}_{N} Y_{1} X_{1}^{d} \cdot 1=\gamma_{N ; t} \boldsymbol{e}_{N} Y_{1} \cdot q^{-d} x_{1}^{d}$.
Applying (2.13) and then 2.9), we find

$$
D_{d, 0}^{(N)} \cdot 1=\gamma_{N ; t} \boldsymbol{e}_{N} t^{(N-1) / 2} T_{1} \cdots T_{N-1} \cdot x_{d}^{d}=\gamma_{N ; t} \boldsymbol{e}_{N} \cdot x_{d}^{d}
$$

By (2.10), we have

$$
\boldsymbol{e}_{N}=\boldsymbol{e}_{[1, N]}=\frac{1-t^{-1}}{1-t^{-N}}\left(\sum_{i=1}^{N} t^{-\frac{N-i}{2}} T_{i} \cdots T_{N-1}\right) \boldsymbol{e}_{[1, N-1]} .
$$

Observe that $\gamma_{N ; t} \frac{1-t^{-1}}{1-t^{-N}}=(1-t) t^{N-1}$. Thus, $\gamma_{N ; t} \boldsymbol{e}_{N}=A_{N} \boldsymbol{e}_{[1, N-1]}$, where we set

$$
A_{M}:=(1-t) t^{M-1}\left(\sum_{i=1}^{M} t^{-\frac{M-i}{2}} T_{i} \cdots T_{M-1}\right) \quad \text { for } 1 \leq M \leq N
$$

(For $i=M$, the term $t^{-\frac{M-i}{2}} T_{i} \cdots T_{M-1}$ is equal to 1.) Thus, $A_{N}=t^{1 / 2} A_{N-1} T_{N-1}+(1-t) t^{N-1}$. Since $\boldsymbol{e}_{[1, N-1]} \cdot x_{N}=x_{N}$, we get

$$
\begin{equation*}
\gamma_{N ; t} \boldsymbol{e}_{[1, N]} \cdot x_{N}^{d}=A_{N} \boldsymbol{e}_{[1, N-1]} \cdot x_{N}^{d}=A_{N} \cdot x_{N}^{d}=t^{1 / 2} A_{N-1} T_{N-1} \cdot x_{N}^{d}+(1-t) t^{N-1} x_{N}^{d} . \tag{2.22}
\end{equation*}
$$

We now prove by induction on $M=1,2, \ldots, N$ that

$$
\begin{equation*}
A_{M} \cdot x_{M}^{d}=(-t)^{d} e_{d}\left[\tilde{\mathbf{X}}_{M}\right], \tag{2.23}
\end{equation*}
$$

where $\tilde{\mathbf{X}}_{M}:=\mathbf{X}_{M}\left(1-t^{-1}\right)$. The desired result follows from (2.23) with $M=N$.
Denote $\tilde{x}_{i}:=x_{i}\left(1-t^{-1}\right)$. By a simple computation as in Ber09, Section 3.8], we see that

$$
\begin{equation*}
(-t)^{d} e_{d}\left[\tilde{x}_{i}\right]=(1-t) x_{i}^{d} \tag{2.24}
\end{equation*}
$$

From here, the base case follows since for $M=1$, both sides of 2.23 become equal to $(1-t) x_{1}^{d}$.

For the induction step, observe that

$$
\begin{equation*}
T_{N-1} x_{N}^{d}=t^{-1 / 2} x_{N-1}^{d}+\left(t^{-1 / 2}-t^{1 / 2}\right)\left(x_{N}^{d}+\sum_{i=1}^{d-1} x_{N-1}^{i} x_{N}^{d-i}\right) \tag{2.25}
\end{equation*}
$$

Each $T_{i}, 1 \leq i<N-1$ treats $x_{N}$ as a constant (although note that $T_{i} \cdot P=t^{-1 / 2} P$ for any polynomial $P$ such that $s_{i} \cdot P=P$ ), and thus $A_{N-1} x_{N}^{d}=\left(1-t^{N-1}\right) x_{N}^{d}$. Combining this with 2.22 and (2.25), we get

$$
A_{N} \cdot x_{N}^{d}=(-t)^{d} e_{d}\left[\tilde{\mathbf{X}}_{N-1}\right]+(1-t) x_{N}^{d}+\sum_{i=1}^{d-1}(-t)^{i} e_{i}\left[\tilde{\mathbf{X}}_{N-1}\right](1-t) x_{N}^{d-i}
$$

By (2.24), we have $(1-t) x_{N}^{k}=(-t)^{k} e_{k}\left[\tilde{x}_{N}\right]$ for all $k \geq 1$. Substituting, we find

$$
A_{N} \cdot x_{N}^{d}=(-t)^{d}\left(e_{d}\left[\tilde{\mathbf{X}}_{N-1}\right]+e_{d}\left[\tilde{x}_{N}\right]+\sum_{i=1}^{d-1} e_{i}\left[\tilde{\mathbf{X}}_{N-1}\right] e_{d-i}\left[\tilde{x}_{N}\right]\right)=(-t)^{d} e_{d}\left[\tilde{\mathbf{X}}_{N}\right]
$$

using $e_{d}[Y+Z]=\sum_{i=0}^{d} e_{d-i}[Y] e_{i}[Z]$; see Hag08, Equation (1.64)].
Recall that for a partition $\lambda=\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{r}\right)$, we have the power sum symmetric function $p_{\lambda}:=p_{\lambda_{1}} p_{\lambda_{2}} \cdots p_{\lambda_{r}}$. Let $|\lambda|$ be the number of boxes in $\lambda, \ell(\lambda)$ be the number of nonzero parts of $\lambda$, and $m_{i}$ be the number of parts of $\lambda$ equal to $i$. We set $\epsilon_{\lambda}:=(-1)^{m_{2}+m_{4}+\cdots}=(-1)^{|\lambda|-\ell(\lambda)}$ and $z_{\lambda}:=1^{m_{1}} m_{1}!2^{m_{2}} m_{2}!\cdots$ as in [Sta99, Section 7.7]. We now express the right-hand side of (2.21) in terms of power sum symmetric functions.

Proposition 2.10 ([Sta99, Proposition 7.7.6]). For all $d \geq 1$,

$$
e_{d}\left[\mathbf{X}\left(1-t^{-1}\right)\right]=\sum_{\lambda \vdash d} p_{\lambda} \epsilon_{\lambda} z_{\lambda}^{-1} \prod_{i}\left(1-t^{-\lambda_{i}}\right)
$$

Finally, for a partition $\lambda=\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{r}\right)$ of $d$, write $P_{d, 0 ; \lambda}^{(N)}:=P_{\lambda_{1}, 0}^{(N)} P_{\lambda_{2}, 0}^{(N)} \cdots P_{\lambda_{r}, 0}^{(N)}$. (The elements $P_{k, 0}^{(N)}$ pairwise commute for different $k$.)
Proposition 2.11. For all $d, N \geq 1$, the element $D_{d, 0}^{(N)}$ is expressed in $\left(P_{k, 0}^{(N)}\right)_{k \geq 0}$ with the same coefficients as $(-t)^{d} e_{d}\left[\mathbf{X}\left(1-t^{-1}\right)\right]$ is expressed in $\left(p_{k}\right)_{k \geq 0}$. Explicitly, we have

$$
\begin{equation*}
D_{d, 0}^{(N)}=\sum_{\lambda \vdash d} c_{\lambda}^{d} P_{d, 0 ; \lambda}^{(N)}, \quad \text { where } \quad c_{\lambda}^{d}=(-t)^{d} \epsilon_{\lambda} z_{\lambda}^{-1} \prod_{i}\left(1-t^{-\lambda_{i}}\right) . \tag{2.26}
\end{equation*}
$$

Proof. We have [SV11, Equation (2.10)]

$$
\begin{equation*}
Y_{1} X_{1} Y_{1}^{-1}=q T_{1} \cdots T_{N-2} T_{N-1}^{2} T_{N-2} \cdots T_{1} X_{1} \tag{2.27}
\end{equation*}
$$

Thus, $D_{d, 0}^{(N)}=q^{d} \gamma_{N ; t} \boldsymbol{e}_{N} D \boldsymbol{e}_{N}$, where $D$ is a product of $T_{i}$-s and $X_{1}$-s. It is clear from (2.12) that for $f \in \mathbb{C}\left[x_{1}, \ldots, x_{N}\right]^{\mathfrak{G}_{N}}$ and $g \in \mathbb{C}\left[x_{1}, \ldots, x_{N}\right], T_{i} \cdot(f g)=f T_{i} \cdot g$. Since $X_{j} \cdot(f g)=$ $q^{-1} x_{j} f g=f X_{j} \cdot g$, we see that for any operator $D$ which is a product of $T_{i}$-s and $X_{j}$-s, $\boldsymbol{e}_{N} D \boldsymbol{e}_{N}$ acts on $\mathbb{C}\left[x_{1}, \ldots, x_{N}\right]^{\mathfrak{G}_{N}}$ as the operator of multiplication by $\boldsymbol{e}_{N} D \boldsymbol{e}_{N} \cdot 1$. It follows that $D_{d, 0}^{(N)}$ acts by multiplication by $(-t)^{d} e_{d}\left[\left(1-t^{-1}\right) \mathbf{X}_{N}\right]$ while $P_{k, 0}^{(N)}$ defined in 2.17) acts by multiplication by $p_{k}\left(x_{1}, \ldots, x_{N}\right)$. It remains to note that the polynomial representation of $\mathbf{S} \ddot{H}_{N ; q, t}^{+}$on $\mathbb{C}\left[x_{1}, \ldots, x_{N}\right]^{\mathfrak{G}_{N}}$ is faithful; cf. [SV13, Section 1.4].

Example 2.12. Let $m=n=1$. We find

$$
\begin{equation*}
(-t)^{1} e_{1}\left[\mathbf{X}_{N}\left(1-t^{-1}\right)\right]=(1-t) p_{1}, \quad \text { and thus } \quad D_{1,1}^{(N)}=(1-t) P_{1}^{(N)} \tag{2.28}
\end{equation*}
$$

Next, let $m=n=2$. Using Proposition 2.10, we find

$$
(-t)^{2} e_{2}\left[\mathbf{X}_{N}\left(1-t^{-1}\right)\right]=\frac{1}{2}\left(1-t^{2}\right) p_{2}+\frac{1}{2}(1-t)^{2} p_{11}
$$

Thus, Proposition 2.11 yields

$$
\begin{equation*}
D_{2,2}^{(N)}=\frac{1}{2}\left(1-t^{2}\right) P_{2,2}^{(N)}+\frac{1}{2}(1-t)^{2}\left(P_{1,1}^{(N)}\right)^{2} \tag{2.29}
\end{equation*}
$$

Proof of Theorem 2.7. By (2.18) and 2.20), for $m, n, N \geq 1$ with $d:=\operatorname{gcd}(m, n)$, we have

$$
\begin{equation*}
D_{m, n}^{(N)}=\sum_{\lambda \vdash d} c_{\lambda}^{d} P_{m, n ; \lambda}^{(N)} \tag{2.30}
\end{equation*}
$$

Here, the coefficients $c_{\lambda}^{d}$ are given in (2.26), and for $\lambda=\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{r}\right)$, we set $P_{m, n ; \lambda}^{(N)}:=$ $P_{\lambda_{1} m_{0}, \lambda_{1} n_{0}}^{(N)} P_{\lambda_{2} m_{0}, \lambda_{2} n_{0}}^{(N)} \cdots P_{\lambda_{r} m_{0}, \lambda_{r} n_{0}}^{(N)}$, where $\left(m_{0}, n_{0}\right):=\frac{1}{d}(m, n)$.

## 3. From DAHA to EHA

In this section, we review the background on the elliptic Hall algebra (EHA) $\mathcal{E}_{q, t}$, introduced in [BS12]. We then explain how the elements $D_{C}^{(N)} \in \mathbf{S H}_{N ; q, t}^{+}$give rise to elements of $\mathcal{E}_{q, t}^{+}$in the limit $N \rightarrow \infty$.
3.1. Generators and relations. For a vector $\boldsymbol{x}=(m, n) \in \mathbb{Z}^{2}$, we write $\mathrm{d}(\boldsymbol{x}):=\operatorname{gcd}(m, n)$, and we call $\boldsymbol{x}$ primitive if $\mathrm{d}(\boldsymbol{x})=1$. By definition, $\mathcal{E}_{q, t}$ is an algebra over $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)$ generated by elements $u_{\boldsymbol{x}}, \boldsymbol{x} \in \mathbb{Z}^{2}$, subject to the following relations (see SV11, Section 1.5] and [MS21, Section 2.1]).

- If $\boldsymbol{x}, \boldsymbol{x}^{\prime}$ belong to the same line in $\mathbb{Z}^{2}$ then $\left[u_{\boldsymbol{x}}, u_{\boldsymbol{x}^{\prime}}\right]=0$.
- Assume that $\boldsymbol{x}$ is primitive and that the triangle with vertices $0, \boldsymbol{x}, \boldsymbol{x}+\boldsymbol{y}$ has no interior lattice points. Then

$$
\begin{equation*}
\left[u_{\boldsymbol{y}}, u_{\boldsymbol{x}}\right]=\epsilon_{\boldsymbol{x}, \boldsymbol{y}} \frac{\theta_{\boldsymbol{x}+\boldsymbol{y}}}{\alpha_{1}} \tag{3.1}
\end{equation*}
$$

where $\epsilon_{\boldsymbol{x}, \boldsymbol{y}}:=\operatorname{sign}(\operatorname{det}(\boldsymbol{x} \boldsymbol{y}))$ and $\theta_{\boldsymbol{z}}, \boldsymbol{z} \in \mathbb{Z}^{2}$ is defined by

$$
\sum_{i=0}^{\infty} \theta_{i z_{0}} z^{i}=\exp \left(\sum_{i=1}^{\infty} \alpha_{i} u_{i z_{0}} z^{i}\right)
$$

Here, $\boldsymbol{z}_{0} \in \mathbb{Z}^{2}$ is primitive and

$$
\begin{equation*}
\alpha_{i}=\frac{1}{i}\left(1-q^{-i}\right)\left(1-t^{-i}\right)\left(1-(q t)^{i}\right) \tag{3.2}
\end{equation*}
$$

It follows directly from the above relations that $\mathrm{SL}_{2}(\mathbb{Z})$ acts on $\mathcal{E}_{q, t}$ by $g \cdot u_{\boldsymbol{x}}=u_{g \cdot \boldsymbol{x} \cdot}$.
Example 3.1. When $\boldsymbol{x}+\boldsymbol{y}$ is primitive, we have $\theta_{\boldsymbol{x}+\boldsymbol{y}}=\alpha_{1}$ and (3.1) becomes

$$
\begin{equation*}
\left[u_{\boldsymbol{y}}, u_{\boldsymbol{x}}\right]=\epsilon_{\boldsymbol{x}, \boldsymbol{y}} u_{\boldsymbol{x}+\boldsymbol{y}} . \tag{3.3}
\end{equation*}
$$

On the other hand, letting $\boldsymbol{x}=(1,0)$ and $\boldsymbol{y}=(1,2)$, we have

$$
\begin{equation*}
u_{2,2}=\frac{2 q t}{(1+q)(1+t)(1+q t)}\left[u_{1,2}, u_{1,0}\right]-\frac{(1-q)(1-t)(1-q t)}{(1+q)(1+t)(1+q t)} u_{1,1}^{2} . \tag{3.4}
\end{equation*}
$$

3.2. Taking the limit. Define the positive parts $\mathbf{S} \ddot{H}_{N ; q, t}^{+} \subset \mathbf{S} \ddot{H}_{N ; q, t}\left(\right.$ resp., $\mathcal{E}_{q, t}^{+} \subset \mathcal{E}_{q, t}$ ) to be the subalgebras generated by the elements $P_{\boldsymbol{x}}^{(N)}$ (resp., $u_{\boldsymbol{x}}$ ) for $\boldsymbol{x} \in \mathbf{Z}^{+}$:

$$
\begin{equation*}
\mathbf{S H}_{N ; q, t}^{+}:=\left\langle P_{\boldsymbol{x}}^{(N)} \mid \boldsymbol{x} \in \mathbf{Z}^{+}\right\rangle \quad \text { and } \quad \mathcal{E}_{q, t}^{+}:=\left\langle u_{\boldsymbol{x}} \mid \boldsymbol{x} \in \mathbf{Z}^{+}\right\rangle . \tag{3.5}
\end{equation*}
$$

By [SV11, Proposition 4.1], we have a surjective algebra map $\mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}^{+} \rightarrow \mathbf{S} \ddot{\mathbf{H}}_{N-1 ; q, t}^{+}, P_{\boldsymbol{x}}^{(N)} \mapsto$ $P_{\boldsymbol{x}}^{(N-1)}$ for all $\boldsymbol{x} \in \mathbf{Z}^{+}$. Let $\mathbf{S} \ddot{\mathbf{H}}_{\infty ; q, t}^{+}$be the corresponding projective limit, generated by $\left\{P_{\boldsymbol{x}} \mid \boldsymbol{x} \in \mathbf{Z}^{+}\right\}$.
Theorem 3.2 ([SV11, Theorem 4.6]). The assignment

$$
\begin{equation*}
u_{\boldsymbol{x}} \mapsto \frac{1}{q^{\mathrm{d}(\boldsymbol{x})}-1} P_{\boldsymbol{x}} \tag{3.6}
\end{equation*}
$$

induces an isomorphism $\mathcal{E}_{q, t}^{+} \xrightarrow{\sim} \mathbf{S} \ddot{\mathbf{H}}_{\infty ; q, t}^{+}$.
In view of (3.6), we denote

$$
\begin{equation*}
P_{\boldsymbol{x}}^{\mathcal{E}}:=\left(q^{\mathrm{d}(\boldsymbol{x})}-1\right) u_{\boldsymbol{x}} . \tag{3.7}
\end{equation*}
$$

According to [SV11, Theorem 3.1], the isomorphism (3.6) is the restriction of a $\mathbb{Z}^{2}$-graded $\mathrm{SL}_{2}(\mathbb{Z})$-equivariant surjective algebra homomorphism $\overline{\mathcal{E}}_{q, t} \rightarrow \mathbf{S H}_{\infty ; q, t}$. In particular, the isomorphism (3.6) commutes with the action of $\mathcal{B}_{3}^{+}$. Applying Theorem 2.7, we obtain the following.

Corollary 3.3. For each $m, n \geq 1$, the sequence $D_{m, n}^{(N)}, N=1,2, \ldots$, gives rise to a welldefined limit $D_{m, n} \in \mathbf{S} \ddot{H}_{\infty ; q, t}^{+}$.

We continue to denote by $D_{m, n} \in \mathcal{E}_{q, t}^{+}$the image of $D_{m, n}$ under the identification $\mathbf{S} \ddot{H}_{\infty ; q, t}^{+} \cong$ $\mathcal{E}_{q, t}^{+}$.
3.3. Action on symmetric functions. We follow the exposition of [SV13]; cf. Remark 2.4 . Consider the automorphism $\theta$ of $\mathbf{S} \ddot{H}_{N ; q, t}^{+}$given by

$$
\theta\left(P_{0, d}^{(N)}\right)=P_{0, d}^{(N)}-\frac{1-t^{d N}}{1-t^{d}}, \quad d \in \mathbb{Z}^{>} ; \quad \theta\left(P_{i, j}^{(N)}\right)=P_{i, j}^{(N)}, \quad(i, j) \in \mathbf{Z}^{>}
$$

Then $\tilde{\phi}_{N}:=\phi_{N} \circ \theta$ is a representation of $\mathbf{S} \ddot{H}_{N ; q, t}^{+}$on $\Lambda_{N ; q, t}$, where $\phi_{N}$ is defined in Section 2.2. Letting $\rho_{N}: \Lambda_{q, t} \rightarrow \Lambda_{N ; q, t}$ be the operator setting $x_{N+1}=x_{N+2}=\cdots=0$, we get $\tilde{\phi}_{N-1}\left(P_{i, j}^{(N-1)}\right) \circ \rho_{N-1}=\rho_{N-1} \circ \tilde{\phi}_{N}\left(P_{i, j}^{(N)}\right) \circ \rho_{N}$ for $(i, j) \in \mathbf{Z}^{+}$. Thus, we may take the limit of $\tilde{\phi}_{N}$ as $N \rightarrow \infty$. The resulting representation $\tilde{\phi}_{\infty}$ of $\mathbf{S} \ddot{H}_{\infty ; q, t}^{+} \cong \mathcal{E}_{q, t}^{+}$on $\Lambda_{q, t}$ may be described explicitly in terms of the Macdonald polynomials $P_{\lambda}(q, t) \in \Lambda_{q, t}$ : for $d \in \mathbb{Z}^{>}$, we have

$$
\begin{equation*}
\tilde{\phi}_{\infty}\left(u_{0, d}\right) \cdot P_{\lambda}\left(q, t^{-1}\right)=\left(\sum_{i} \frac{q^{d \lambda_{i}}-1}{q^{d}-1} t^{d(i-1)}\right) P_{\lambda}\left(q, t^{-1}\right) \tag{3.8}
\end{equation*}
$$

and $\tilde{\phi}_{\infty}\left(u_{1,0}\right)$ is the operator of multiplication by $\frac{1}{q-1} p_{1}$; see [SV13, Corollary 1.5].
Remark 3.4. Observe from (3.2) that the parameters $q, t,(q t)^{-1}$ enter symmetrically into the definition of $\mathcal{E}_{q, t}$. Even though it may appear that (3.8) breaks the $q, t$-symmetry, note that the plethysm $\left[\frac{\mathbf{X}}{1-t}\right]$ from (1.10) turns Macdonald polynomials $P_{\lambda}$ into modified Macdonald polynomials $\tilde{H}_{\lambda}$. Using the well-known $q, t$-symmetry $\tilde{H}_{\lambda}(q, t)=\tilde{H}_{\lambda^{\prime}}(t, q)$ (where $\lambda^{\prime}$ denotes the conjugate partition), one may deduce that the symmetric function $F_{C}$ is $q, t$-symmetric ${ }^{6}$ Alternatively, $q, t$-symmetry of $F_{C}$ may be seen directly from (7.7). See also [GN15, Section 6.2].

## 4. Skein relation

The goal of this section is to prove Theorem 1.7. We will give an algebraic proof based on the diagrammatic formalism of Morton-Samuelson [MS21; see Section 5 and Remark 5.12 . Along the way, we will also prove Theorem 1.6. We start with a version of Theorem 1.7 for finite $N$.

Theorem 4.1. Consider curves $C_{+}, C_{-}, C_{0}$ which pass above, below, and through some lattice point $\boldsymbol{p}$ as in Theorem 1.7. Then

$$
\begin{equation*}
D_{C_{+}}^{(N)}=q t D_{C_{-}}^{(N)}+D_{C_{0}}^{(N)} . \tag{4.1}
\end{equation*}
$$

Proof. Consider the elements $D_{C_{+}}^{(N)}, D_{C_{-}}^{(N)}, D_{C_{0}}^{(N)} \in \mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$ associated to $C_{+}, C_{-}, C_{0}$ via Definition 1.3. The paths $\mathcal{P}_{C_{+}}, \mathcal{P}_{C_{-}}, \mathcal{P}_{C_{0}}$ differ locally so that $\mathcal{P}_{C_{+}}=\cdots U R \cdots, \mathcal{P}_{C_{-}}=\cdots R U \cdots$, $\mathcal{P}_{C_{0}}=\cdots U * R \cdots$, where $U$ and $R$ indicate up and right steps, respectively, and $*$ indicates

[^4]that $\mathcal{P}_{C_{0}}$ passes through the lattice point $\boldsymbol{p}$. In particular, the elements $D_{C_{+}}^{(N)}, D_{C_{-}}^{(N)}, D_{C_{0}}^{(N)}$ are given by
$D_{C_{+}}^{(N)}=A Y_{1} Y_{1} X_{1} Y_{1}^{-1} B, \quad D_{C_{-}}^{(N)}=A Y_{1} X_{1} Y_{1}^{-1} Y_{1} B, \quad$ and $\quad D_{C_{0}}^{(N)}=A Y_{1} \cdot \gamma_{N ; t} \boldsymbol{e}_{N} \cdot Y_{1} X_{1} Y_{1}^{-1} B$ for some $A, B \in \mathbf{S H}_{N ; q, t}$. According to Definition $1.3, A=\gamma_{N ; t} \boldsymbol{e}_{N} A^{\prime}$ for some $A^{\prime} \in \mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$. We have $\boldsymbol{e}_{N}=\boldsymbol{e}_{[1, N]}=\boldsymbol{e}_{[1, N]} \boldsymbol{e}_{[2, N]}$, and $\boldsymbol{e}_{[2, N]}$ commutes with $X_{1}, Y_{1}$, and $\boldsymbol{e}_{N}$. Thus, we have $A Y_{1}=A Y_{1} \boldsymbol{e}_{[2, N]}$. Applying (2.27), we find
$$
D_{C_{+}}^{(N)}=A Y_{1} Y_{1} X_{1} Y_{1}^{-1} B=A Y_{1} \cdot \boldsymbol{e}_{[2, N]} \cdot q T_{1} T_{2} \cdots T_{N-1} T_{N-1} \cdots T_{2} T_{1} X_{1} \cdot B
$$

Applying (2.11) for $k=1$, we get
$D_{C+}^{(N)}=q A Y_{1} \cdot\left(-t\left(1-t^{-N}\right) \boldsymbol{e}_{N}+t \boldsymbol{e}_{[2, N]}\right) X_{1} \cdot B=q t^{-N+1} \gamma_{N ; t} A Y_{1} \cdot \boldsymbol{e}_{N} X_{1} \cdot B+q t A Y_{1} \cdot \boldsymbol{e}_{[2, N]} X_{1} \cdot B$.
Since $A Y_{1}=A Y_{1} \boldsymbol{e}_{[2, N]}$, the second term on the right-hand side becomes $q t A Y_{1} X_{1} B=q t D_{C_{-}}^{(N)}$. We claim that the first term equals $D_{C_{0}}^{(N)}$. Indeed, by (2.27) and 2.9), we get

$$
\begin{aligned}
D_{C_{0}}^{(N)} & =A Y_{1} \cdot \gamma_{N ; t} \boldsymbol{e}_{N} \cdot Y_{1} X_{1} Y_{1}^{-1} B=A Y_{1} \cdot \gamma_{N ; t} \boldsymbol{e}_{N} \cdot q T_{1} T_{2} \cdots T_{N-1} T_{N-1} \cdots T_{2} T_{1} X_{1} \cdot B \\
& =q t^{-N+1} \gamma_{N ; t} A Y_{1} \cdot \boldsymbol{e}_{N} X_{1} \cdot B .
\end{aligned}
$$

This proves (4.1). See Figure 9 for a diagrammatic interpretation of the above argument.
Proof of Theorems 1.6 and 1.7 . As explained in Remark 1.10 , each element $D_{C}^{(N)}$ may be expressed via (4.1) in terms of products of almost linear elements $D_{m_{0}, n_{0}}^{(N)}$ with coefficients not depending on $N$. By Corollary 3.3 , for each curve $C$, we get a well-defined limit $D_{C} \in \mathbf{S} \ddot{\mathbf{H}}_{\infty ; q, t}^{+}$ of $D_{C}^{(N)}$ as $N \rightarrow \infty$. This shows Theorem 1.6. The resulting limiting elements satisfy (1.9) by construction, which shows Theorem 1.7.

Example 4.2. We calculate the elements $D_{C_{+}}, D_{C_{-}}, D_{C_{0}}$ for the three curves in Figure 3. By (1.8), (2.28), and (3.7), we have

$$
D_{C_{0}}=D_{1,1}^{2}=(1-t)^{2}(q-1)^{2} u_{1,1}^{2} .
$$

Next, by (2.29) and (3.7), we find

$$
D_{C_{+}}=D_{2,2}=\frac{1}{2}\left(1-t^{2}\right)\left(q^{2}-1\right) u_{2,2}+\frac{1}{2}(1-t)^{2}(q-1)^{2} u_{1,1}^{2} .
$$

Therefore, by (1.9),

$$
D_{C_{-}}=\frac{1}{2 q t}\left(1-t^{2}\right)\left(q^{2}-1\right) u_{2,2}-\frac{1}{2 q t}(1-t)^{2}(q-1)^{2} u_{1,1}^{2} .
$$

We may now compute the symmetric functions $F_{C_{+}}, F_{C_{-}}, F_{C_{0}}$. One way to do that is by using the polynomial representation of the DAHA, i.e., by combining Example 1.4 with Section 2.2. Alternatively, we can use commutation relations, such as (3.4), together with Section 3.3. Both computations lead to the following result:

$$
\begin{align*}
D_{C_{+}} \cdot 1 & =(1-t)\left(\left(1-t^{2}-q t\right) s_{11}+q s_{2}\right) ;  \tag{4.2}\\
D_{C_{-}} \cdot 1 & =(1-t)\left(-t s_{11}+s_{2}\right) ;  \tag{4.3}\\
D_{C_{0}} \cdot 1 & =(1-t)^{2}\left((1+t-q t) s_{11}+q s_{2}\right) . \tag{4.4}
\end{align*}
$$

Applying the plethysm (1.10) yields (1.17), and applying (1.11) yields (1.18).

For a $\mathbb{Z}$-convex curve $C$, Remark 1.10 may be used to obtain a non-recursive formula expressing $D_{C}$ in terms of piecewise almost linear convex curves.

Corollary 4.3. Let $C$ be a $\mathbb{Z}$-convex curve passing through no lattice points other than ( 0,0 ) and $(m, n)$. Then

$$
D_{C}=\sum_{\substack{C^{\prime}=\left[C_{1}^{\prime} C_{2}^{\prime} \ldots C_{k}^{\prime}\right] \\ \mathbb{Z} \text {-conwer }}} \frac{(-1)^{k-1}}{(q t)^{k-1+a\left(C, C^{\prime}\right)}} \cdot D_{C_{1}^{\prime}} \cdot D_{C_{2}^{\prime}} \cdots D_{C_{k}^{\prime}}
$$

where the summation is over all $\mathbb{Z}$-convex piecewise almost linear curves $C^{\prime}$ weakly above $C$, $k=\mathrm{k}\left(C^{\prime}\right)$ is arbitrary, and $a\left(C, C^{\prime}\right)$ is the number of lattice points strictly between $C$ and $C^{\prime}$.

Proof. By (1.8), we have $D_{C^{\prime}}=D_{C_{1}^{\prime}} \cdot D_{C_{2}^{\prime}} \cdots D_{C_{k}^{\prime}}$. The result is obtained by induction on the number of lattice points between $C$ and the almost linear curve from $(0,0)$ to $(m, n)$. For the base case, when $C$ is itself almost linear, the result is vacuously true. The induction step consists of applying 4.1).

We now translate Proposition 2.11 via (3.6) to express the almost linear elements $D_{d x}$ in terms of the renormalized generators $P_{x}^{\mathcal{E}} \in \mathcal{E}_{q, t}$ introduced in (3.7).
Corollary 4.4. For all $d \geq 1$ and primitive $\boldsymbol{x} \in \mathbf{Z}^{+}$, the element $D_{d \boldsymbol{x}}$ is expressed in $\left(P_{k x}^{\mathcal{E}}\right)_{k \geq 0}$ with the same coefficients as $(-t)^{d} e_{d}\left[\mathbf{X}\left(1-t^{-1}\right)\right]$ is expressed in $\left(p_{k}\right)_{k \geq 0}$.

## 5. Skein algebras and modules

We review the background on the skein-theoretic approach of MS17, MS21 and use it to prove Theorem 1.5 .
5.1. Skein of a surface. Let $\mathbb{S}$ be a surface. A framed (oriented) link $L$ is an embedding of a disjoint union of several ribbons $S^{1} \times[0,1]$ into $\mathbb{S} \times[0,1]$, where each component of $L$ is the image of $S^{1} \times\{1 / 2\}$. If an unframed oriented link $L$ is drawn in the plane, we often equip it with the blackboard framing, so that each ribbon is obtained by taking a thin neighborhood of the corresponding component of $L$ in the plane.
Definition 5.1. The skein algebra $\mathrm{Sk}_{q^{-1}}(\mathbb{S})$ is the algebra of $\mathbb{C}\left(v, q^{1 / 2}\right)$-linear combinations of isotopy classes of framed oriented links inside $\mathbb{S} \times[0,1]$ subject to the relations

Since the relation (5.1) preserves homology classes of curves, we see that $\mathrm{Sk}_{q^{-1}}(\mathbb{S})$ is $H_{1}(\mathbb{S})$ graded.

We will be interested in the surfaces $\mathbb{S} \in\{\mathbb{T}-\mathbb{D}, \mathbb{T}, \mathbb{A}, \mathbb{D}\}$, where $\mathbb{T}=\mathbb{R}^{2} / \mathbb{Z}^{2}$ is a torus, $\mathbb{A}=(\mathbb{R} / \mathbb{Z}) \times[0,1]$ is an annulus, and $\mathbb{D}$ is a two-dimensional disk.
5.1.1. Disk. The HOMFLY polynomial $\mathcal{P}(L)=\mathcal{P}_{L}^{\text {HOMFLY }}(a, q)$ of an (oriented, unframed) link $L$ in a disk is defined by the skein recurrence

$$
\begin{equation*}
a \mathcal{P}(\bigwedge)-a^{-1} \mathcal{P}\left(\boldsymbol{\chi}^{\boldsymbol{X}}\right)=\left(q^{-1 / 2}-q^{1 / 2}\right) \mathcal{P}()() \quad \text { and } \quad \mathcal{P}(\bigcirc)=\frac{a-a^{-1}}{q^{-1 / 2}-q^{1 / 2}} \tag{5.2}
\end{equation*}
$$

Here, $\bigcirc$ denotes the unknot, and this normalization is chosen so that the value of $\mathcal{P}$ on the empty link is equal to 1 .

In order to relate the variable $v$ in (5.1) to the variable $a$ in (5.2), we apply MS17, Theorem 6.1]. Given a framed link $L$ in $\mathbb{D}$, let $L^{\prime}$ be a (link diagram of a framed) link isotopic to $L$ such that the framing of $L^{\prime}$ coincides with the blackboard framing. Then define the writhe $\mathrm{w}(L) \in \mathbb{Z}$ of $L$ to be the number of positive crossings in $L^{\prime}$ minus the number of negative crossings in $L^{\prime}$. Applying [MS17, Theorem 6.1] and using the fact that (5.2) gives rise to a well-defined link invariant, we find that the identity

$$
\begin{equation*}
\left.L\right|_{v=a^{-1}}=a^{\mathrm{w}(L)} \mathcal{P}_{L}^{\mathrm{HOMFLY}}(a, q) \tag{5.3}
\end{equation*}
$$

holds inside $\mathrm{Sk}_{q^{-1}}(\mathbb{D})$, where $L$ is an arbitrary framed link and the right-hand side is considered as a multiple of the empty link.
5.1.2. Annulus. The positive part $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A}) \subset \mathrm{Sk}_{q^{-1}}(\mathbb{A})$ consists of linear combinations of links whose lift to the universal cover $\mathbb{R} \times[0,1]$ only intersects vertical grid lines $x=k$, $k \in \mathbb{Z}$ from left to right.

The algebra $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A})$ is easily seen to be commutative. One may view it as the algebra of linear combinations of closures of $N$-strand braids, where $N=0,1,2, \ldots$.

Theorem 5.2 ([Tur88, Ais96, AM98]). The algebra $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A})$ is isomorphic to the algebra $\Lambda_{q}$ of symmetric functions over $\mathbb{C}\left(q^{1 / 2}\right)$.

We describe this isomorphism explicitly in two different ways. First, for each $N=$ $0,1,2, \ldots$, let

$$
\begin{equation*}
W_{N ; q}^{\mathbb{A}}:=\frac{q^{1 / 2}-q^{-1 / 2}}{q^{N / 2}-q^{-N / 2}} \sum_{i=0}^{N-1} A_{i, N-1-i}, \tag{5.4}
\end{equation*}
$$

where $A_{i, N-1-i}$ is the annular closure of the braid $\sigma_{1} \cdots \sigma_{i} \cdot \sigma_{i+1}^{-1} \cdots \sigma_{N-1}^{-1}$; see the figure above [MS17, Remark 2.4].

Notation 5.3. In our figures, the generators $\sigma_{i}$ of $\mathcal{B}_{N}$ are depicted with positive crossings $\mathcal{Y}$; cf. Notation 5.9. The homomorphism $\mathcal{B}_{N} \rightarrow \mathbf{H}_{N ; q^{-1}}$ sends $\sigma_{i} \mapsto T_{i}^{-1}$.
Remark 5.4. The braids $\beta_{i, N-1-i}:=\sigma_{1} \cdots \sigma_{i} \cdot \sigma_{i+1}^{-1} \cdots \sigma_{N-1}^{-1}$ and $\beta_{N-1-i, i}^{\prime}:=\sigma_{1}^{-1} \cdots \sigma_{N-1-i}^{-1}$. $\sigma_{N-i} \cdots \sigma_{N-1}$ are conjugate, and thus the element $W_{N ; q}^{\mathrm{A}}$ does not depend on whether one takes $A_{i, N-1-i}$ to be the annular closure of $\beta_{i, N-1-i}$ or of $\beta_{N-1-i, i}^{\prime}$.

By definition, the isomorphism of Theorem 5.2 sends

$$
\begin{equation*}
W_{N ; q}^{\mathrm{A}} \mapsto p_{N} \quad \text { for } N=0,1, \ldots \tag{5.5}
\end{equation*}
$$

(For $N=0$, we set $W_{0 ; q}^{\mathbb{A}}:=1 \in \mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A})$ and $p_{0}:=1 \in \Lambda_{q}$.)
Alternatively, let $\mathbf{H}_{N ; q^{-1}}$ be the Hecke algebra generated by $T_{1}, \ldots, T_{N-1}$ modulo relations

$$
\begin{equation*}
T_{i} T_{i+1} T_{i}=T_{i+1} T_{i} T_{i+1} \quad \text { and } \quad\left(T_{i}-q^{1 / 2}\right)\left(T_{i}+q^{-1 / 2}\right)=0 \tag{5.6}
\end{equation*}
$$

Note that the second relation is equivalent to $T_{i}^{-1}-T_{i}=\left(q^{-1 / 2}-q^{1 / 2}\right)$; cf. (5.1) and Notation 2.2. Upon setting $q=t^{-1}$, we recover the relation (2.1).

The algebra $\mathrm{Sk}_{q^{-1}}(\mathbb{A})$ is $H_{1}(\mathbb{A})=\mathbb{Z}$-graded, and the graded piece of $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A})$ of degree $m \geq 0$ is isomorphic (as a vector space over $\mathbb{C}\left(v, q^{1 / 2}\right)$ ) to $\mathbf{H}_{m ; q^{-1}}^{\prime} \otimes \mathbb{C}(v)$, where $\mathbf{H}_{m ; q^{-1}}^{\prime}:=$
$\mathbf{H}_{m ; q^{-1}} /\left[\mathbf{H}_{m ; q^{-1}}, \mathbf{H}_{m ; q^{-1}}\right]$. We thus have an identification

$$
\begin{equation*}
\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A}) \cong \bigoplus_{m=0}^{\infty} \mathbf{H}_{m ; q^{-1}}^{\prime} \otimes \mathbb{C}(v) \tag{5.7}
\end{equation*}
$$

The irreducible representations $V_{\lambda}$ of $\mathbf{H}_{m ; q^{-1}}$ are well known GP93 to be indexed by Young diagrams $\lambda$ with $m$ boxes. For instance, the trivial representation $V_{(m)}$ (resp., the sign representation $V_{\left(1^{m}\right)}$ ) is the one-dimensional representation where each $T_{i}$ acts by multiplication by $q^{1 / 2}$ (resp., by $-q^{-1 / 2}$ ).

Define a map

$$
\begin{equation*}
\operatorname{Tr}_{\Lambda_{q}}: \mathbf{H}_{m ; q^{-1}} \rightarrow \Lambda_{q}, \quad x \mapsto \sum_{\lambda \vdash m} \operatorname{Tr}\left(x ; V_{\lambda}\right) s_{\lambda}, \tag{5.8}
\end{equation*}
$$

where $s_{\lambda}$ is a Schur function [Sta99, Section 7.10]. Clearly, this map factors through the quotient map $\mathbf{H}_{m ; q^{-1}} \rightarrow \mathbf{H}_{m ; q^{-1}}^{\prime}$.

The map $\operatorname{Tr}_{\Lambda_{q}}$ composed with (5.7) gives another description of the isomorphism of Theorem 5.2.

Proposition 5.5 ([GW23, Corollary 2.22]). The isomorphism (5.5) coincides with the composition of (5.7) and (5.8).7
Example 5.6. For $N=2$, the only two irreducible representations of the Hecke algebra $\mathbf{H}_{2 ; q^{-1}}$ are $V_{2}$ (trivial) and $V_{11}$ (sign). Thus,

$$
\begin{equation*}
\operatorname{Tr}_{\Lambda_{q}}\left(T_{1}^{r}\right)=(-1)^{r} q^{-\frac{r}{2}} s_{11}+q^{\frac{r}{2}} s_{2} \quad \text { for all } r \in \mathbb{Z} \tag{5.9}
\end{equation*}
$$

On the other hand, (5.4) gives $W_{2 ; q}^{\mathbb{A}}=\frac{1}{q^{1 / 2}+q^{-1 / 2}}\left(T_{1}+T_{1}^{-1}\right)$, under the identification (5.7). Thus,

$$
\operatorname{Tr}_{\Lambda_{q}}\left(W_{2 ; q}^{\mathbb{A}}\right)=-s_{11}+s_{2}=p_{2},
$$

in agreement with Proposition 5.5.
We can also relate $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A})$ to $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{D})$ as follows. Observe that any embedding $\mathbb{S} \rightarrow \mathbb{S}^{\prime}$ of surfaces gives rise to a homomorphism

$$
\begin{equation*}
\mathrm{Sk}_{q^{-1}}(\mathbb{S}) \rightarrow \mathrm{Sk}_{q^{-1}}\left(\mathbb{S}^{\prime}\right) \tag{5.10}
\end{equation*}
$$

of the associated skein algebras. In particular, identifying $\mathbb{A}$ with $\mathbb{D}-\epsilon \mathbb{D}$ for some $0<\epsilon<1$, we obtain an algebra homomorphism

$$
\begin{equation*}
\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A}) \rightarrow \mathrm{Sk}_{q^{-1}}(\mathbb{D}) \tag{5.11}
\end{equation*}
$$

5.1.3. Torus. The algebra $\mathrm{Sk}_{q^{-1}}(\mathbb{T})$ is generated by certain elements $W_{\boldsymbol{x} ; q}^{\mathbb{T}}, \boldsymbol{x} \in \mathbf{Z}^{*}$, defined as follows. (See [MS17] for a beautiful description of relations between these elements.) When $\boldsymbol{x}$ is primitive, we let $W_{\boldsymbol{x} ; q}^{\mathbb{T}}$ correspond to the embedded curve of homology class $\boldsymbol{x}$. Suppose now that $\boldsymbol{x}=k \boldsymbol{x}_{0}$, where $k \geq 1$ and $\boldsymbol{x}_{0}$ is primitive. Consider a primitive curve $C_{\boldsymbol{x}_{0}}$ of homology class $\boldsymbol{x}_{0}$. For $N \geq 1$ and a braid $\beta \in \mathcal{B}_{N}$, we may consider a $\beta$-decoration of $C_{\boldsymbol{x}_{0}}$, which is obtained by taking the image of the annular closure of $\beta$ inside $\mathbb{A}$ under the homeomorphism from $\mathbb{A}$ to a small neighborhood of $C_{\boldsymbol{x}_{0}}$. We extend this construction to linear combinations of braids, and define $W_{\boldsymbol{x} ; q}^{\mathbb{T}}$ as the $W_{k ; q}^{\mathbb{A}}$-decoration of $C_{\boldsymbol{x}_{0}}$.

[^5]

Figure 6. Wrapping the torus around the annulus; see Definition 5.7.
The algebra $\mathrm{Sk}_{q^{-1}}(\mathbb{T})$ is $H_{1}(\mathbb{T})=\mathbb{Z}^{2}$-graded. We let $\psi_{v}: \mathrm{Sk}_{q^{-1}}(\mathbb{T}) \xrightarrow{\sim} \mathrm{Sk}_{q^{-1}}(\mathbb{T})$ be the graded automorphism multiplying each ( $i, j$ )-graded component by $v^{j}$.

Definition 5.7. The action of $\mathrm{Sk}_{q^{-1}}(\mathbb{T})$ on $\mathrm{Sk}_{q^{-1}}(\mathbb{A})$ is obtained by first applying $\psi_{v}$ and then "wrapping $\mathbb{T}$ around $\mathbb{A}$ " as shown in Figure 6. More precisely, $\mathrm{Sk}_{q^{-1}}(\mathbb{A})$ consists of framed links inside $\mathbb{A} \times[0,1]$, and $\mathbb{A} \times[0,1]$ is homeomorphic to the solid torus $S^{1} \times \mathbb{D}$. Identifying $\mathbb{T}$ with the boundary of $S^{1} \times \mathbb{D}$, we obtain the desired action. See Definition 6.5 for a more precise description.

The positive part $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{T}) \subset \mathrm{Sk}_{q^{-1}}(\mathbb{T})$ consists of linear combinations of elements $W_{\boldsymbol{x} ; q}^{\mathbb{T}}$ for $\boldsymbol{x} \in \mathbf{Z}^{+}$. In particular, the action of $\mathrm{Sk}_{q^{-1}}(\mathbb{T})$ on $\mathrm{Sk}_{q^{-1}}(\mathbb{A})$ restricts to an action of $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{T})$ on $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A})$.
5.1.4. Punctured torus. Let $\mathbb{T}-\mathbb{D}$ be the punctured torus, obtained from $\mathbb{T}$ by removing a small disk $\mathbb{D}$. We consider the algebra $\mathrm{Sk}_{t}(\mathbb{T}-\mathbb{D})$. Let $\boldsymbol{x} \in \mathbf{Z}^{*}$, and suppose that $\boldsymbol{x}=k \boldsymbol{x}_{0}$ with $\boldsymbol{x}_{0}$ primitive and $k \geq 1$. Let $C_{\boldsymbol{x}_{0}}$ be a primitive curve of homology class $\boldsymbol{x}_{0}$ avoiding the puncture $\mathbb{D}$. As before, we let $W_{\boldsymbol{x} ; t^{-1}}^{\mathbb{T}-\mathbb{D}} \in \mathrm{Sk}_{t}(\mathbb{T}-\mathbb{D})$ be obtained by decorating the curve $C_{\boldsymbol{x}_{0}}$ by the element $W_{k ; t^{-1}}^{\mathbb{A}}$.

Applying (5.10) to the inclusion $\mathbb{T}-\mathbb{D} \hookrightarrow \mathbb{T}$, we get a homomorphism

$$
\begin{equation*}
\mathrm{Sk}_{t}^{+}(\mathbb{T}-\mathbb{D}) \rightarrow \mathrm{Sk}_{t}^{+}(\mathbb{T}) \tag{5.12}
\end{equation*}
$$

Morton-Samuelson [MS21, Definition 5.6] define the positive part $\mathrm{Sk}_{t}^{+}(\mathbb{T}-\mathbb{D}) \subset \mathrm{Sk}_{t}(\mathbb{T}-\mathbb{D})$ to be the subalgebra generated by $W_{\boldsymbol{x} ; t^{-1}}^{\mathbb{T}-\mathbb{D}}, \boldsymbol{x} \in \mathbf{Z}^{+}$.
5.2. Braid and tangle skein algebras. We recall the construction of MS21, Section 3.1] of the braid skein algebra $\mathrm{BSk}_{N ; q, t}(\mathbb{T}, *)$ of a torus $\mathbb{T}$. Let $N \geq 1$ and $0<\epsilon<1$. Place $N$ points $\boldsymbol{p}_{i}:=\frac{\epsilon}{N+1}(i, i), i=1,2, \ldots, N$ in $\mathbb{T}$, and let $\boldsymbol{p}_{*}:=(\epsilon, \epsilon)$. The base string is the line segment $\boldsymbol{p}_{*} \times[0,1] \subset \mathbb{T} \times[0,1]$. By definition, a braid is a collection of $N$ curves in $\mathbb{T} \times[0,1]$ connecting $\left\{\left(\boldsymbol{p}_{1}, 0\right), \ldots,\left(\boldsymbol{p}_{N}, 0\right)\right\}$ to $\left\{\left(\boldsymbol{p}_{1}, 1\right), \ldots,\left(\boldsymbol{p}_{N}, 1\right)\right\}$ (in some order), so that the $[0,1]$-coordinate of each curve is monotone increasing. The curves are required to be disjoint from each other and from the base string. See Figure 7 for examples.

Let $\mathrm{BSk}_{N ; q, t}(\mathbb{T}, *)$ consist of $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)$-linear combinations of such braids subject to the local relations

$$
\begin{equation*}
\left.\boldsymbol{X}-\boldsymbol{\lambda}=\left(t^{1 / 2}-t^{-1 / 2}\right)\right)\left(\text { and } \boldsymbol{X}_{*}=q^{-1} \boldsymbol{X}_{*}\right. \tag{5.13}
\end{equation*}
$$

where $*$ denotes the base string. The first relation coincides with (1.1). The multiplication comes from stacking in the $[0,1]$ direction.


Figure 7. The toric braids $T_{i}, X_{i}, Y_{i}$ from Definition 5.8.
Definition 5.8. We have braids $T_{i}$ for $i=1,2, \ldots, N-1$ and $X_{i}, Y_{i}$ for $i=1,2, \ldots, N$ shown in Figure 7 :

- $T_{i}$ rotates the points $\boldsymbol{p}_{i}$ and $\boldsymbol{p}_{i+1}$ clockwise;
- $X_{i}$ moves the point $\boldsymbol{p}_{i}$ to the right by vector $(1,0)$;
- $Y_{i}$ moves the point $\boldsymbol{p}_{i}$ up by vector $(0,1)$.

Notation 5.9. Our notation is obtained from that of MS21] by substituting $\left(x_{i}, y_{i}, \sigma_{i}, c, s\right) \mapsto$ $\left(X_{i}, Y_{i}, T_{i}^{-1}, q^{-1 / 2}, t^{1 / 2}\right)$. In particular, their generators $\sigma_{i}$ are represented by positive crossings, in agreement with Notation 2.2.

Theorem 5.10 ([MS21, Theorem 3.7]). The map $\left(T_{i}, X_{i}, Y_{i}\right) \mapsto\left(T_{i}, X_{i}, Y_{i}\right)$ induces an isomorphism

$$
\begin{equation*}
\mathrm{BSk}_{N ; q, t}(\mathbb{T}, *) \xrightarrow{\sim} \ddot{\mathbf{H}}_{N ; q, t} . \tag{5.14}
\end{equation*}
$$

Next, we consider the algebra $\mathrm{Sk}_{N ; q, t}(\mathbb{T}, *)$ of framed tangles. By definition, a tangle is a collection of $N$ oriented curves in $\mathbb{T} \times[0,1]$ connecting $\left\{\left(\boldsymbol{p}_{1}, 0\right), \ldots,\left(\boldsymbol{p}_{N}, 0\right)\right\}$ to $\left\{\left(\boldsymbol{p}_{1}, 1\right), \ldots,\left(\boldsymbol{p}_{N}, 1\right)\right\}$, together with some closed curves in $\mathbb{T} \times[0,1]$. As before, the curves are required to be disjoint from each other and from the base string. (However, they are no longer required to be monotone in the $[0,1]$ direction.) In a framed tangle, each curve is additionally given together with a framing. The algebra $\mathrm{Sk}_{N ; q, t}(\mathbb{T}, *)$ consists of $\mathbb{C}\left(q^{1 / 2}, t^{1 / 2}\right)$-linear combinations of such framed tangles modulo the relations (5.13), and the multiplication again comes from stacking in the $[0,1]$ direction.

By MS21, Theorem 4.1], we have a homomorphism

$$
\begin{equation*}
\operatorname{BSk}_{N}(\mathbb{T}, *) \rightarrow \mathrm{Sk}_{N ; q, t}(\mathbb{T}, *) \tag{5.15}
\end{equation*}
$$

obtained by taking a braid and choosing its framing in a canonical way: for instance, one can let the framing be spanned by the braid strand and the vector $(1,0,0)$, which is never


Figure 8. Toric braids and tangles in the proof of Theorem 1.5, each shown in plan view and front view; cf. Figure 7(a).
tangent to the strand. By MS21, Theorem 4.2], this homomorphism is surjective. That is, given a framed tangle, one can apply the skein relations (5.13) to express it as a linear combination of braids equipped with canonical framing. It turns out that this map is actually an isomorphism.
Theorem 5.11 ([MS21, Conjecture 1.5] and BCMN23, Theorem 5.10]). The map (5.15) is an isomorphism.
5.3. From monotone curves to DAHA. Let $C$ be a primitive curve given as a plot of a monotone function $f:[0, m] \rightarrow[0, n]$. Recall from Section 1.2 that we may consider a curve $C_{1}$ in $\mathbb{T} \times[0,1]$ parameterized by $C_{1}(t)=(x, f(x), x / m)$ for $x \in[0, m]$. The curve $C_{1}$ connects $(0,0,0)$ to $(m, n, 1)=(0,0,1)$ in $\mathbb{T} \times[0,1]$. Let $C_{2}$ be a vertical line segment connecting $(0,0,1)$ to $(0,0,0)$. The union $C^{\mathbb{T}}:=C_{1} \cup C_{2}$ is a closed curve in $\mathbb{T} \times[0,1]$.

Suppose that $\mathbb{T}-\mathbb{D}$ is a punctured torus such that the puncture $\mathbb{D}$ contains the line segment $\left[0, \boldsymbol{p}_{*}\right]$, where $\boldsymbol{p}_{*}=(\epsilon, \epsilon)$. For $N \geq 1$, we have a homomorphism

$$
\begin{equation*}
\mathrm{Sk}_{t}^{+}(\mathbb{T}-\mathbb{D}) \rightarrow \mathrm{Sk}_{N ; q, t}(\mathbb{T}, *) \tag{5.16}
\end{equation*}
$$

obtained by inserting the identity $N$-braid with a base string into $\mathbb{D}$; see Figure 8(a),
Let $C$ be a primitive curve, and consider the curves $C_{ \pm}$obtained by shifting $C$ by ( $\mp \epsilon, \pm \epsilon$ ) as in Section 1.3. Thus, we may consider the elements $C_{ \pm}^{\mathbb{T}-\mathbb{D}} \in \mathrm{Sk}_{t}(\mathbb{T}-\mathbb{D})$ and $C^{\mathbb{T}-\mathbb{D}} \in$ $\mathrm{Sk}_{q, t}(\mathbb{T}-\mathbb{D})$ defined in Section 1.3. The map (1.5) is the composition

$$
\begin{equation*}
\mathrm{Sk}_{q, t}(\mathbb{T}-\mathbb{D}) \rightarrow \mathrm{Sk}_{N ; q, t}(\mathbb{T}, *) \xrightarrow{\sim} \mathrm{BSk}_{N ; q, t}(\mathbb{T}, *) \xrightarrow{\sim} \ddot{\mathbf{H}}_{N ; q, t} \rightarrow \mathrm{~S}_{\mathbf{H}_{N ; q, t}} . \tag{5.17}
\end{equation*}
$$

of (5.16), the inverse of (5.15), (5.14), and the idempotent projection $\ddot{\mathbf{H}}_{N ; q, t} \rightarrow \mathbf{S} \ddot{\mathbf{H}}_{N ; q, t}$, $x \mapsto \boldsymbol{e}_{N} x \boldsymbol{e}_{N}$.

Proof of Theorem 1.5. Let $C$ be a primitive curve. Recall from Definition 1.3 that $\mathcal{P}_{C}$ is the highest up-right lattice path below $C$. The neighborhood of the corner (i.e., the beginning and the end) of $C_{+}^{\mathbb{T}-\mathbb{D}}$ (resp., $C_{-}^{\mathbb{T}-\mathbb{D}}$ ) is shown in Figure 8(a) (resp., Figure 8(c)).


Figure 9. A diagrammatic proof of the skein relation (1.9) (front view); cf Remark 5.12. Compare with Hog18 or EH19, Equation (1.2)].

For $i=0,1, \ldots, N$, let $C_{i ;+}^{\mathbb{T}-\mathbb{D}}$ be obtained by replacing the leftmost $i$ undercrossings in Figure 8(a), front view, with overcrossings; see Figure 8(b) and (5.4). For $i=1, \ldots, N$, let $Z_{i}^{\mathbb{T}-\mathbb{D}}$ be obtained from $C_{i ;+}^{\mathbb{T}-\mathbb{D}}$ by uncrossing the $i$-th overcrossing; see Figure 8(d). Thus, $C_{0 ;+}^{\mathbb{T}-\mathbb{D}}=C_{+}^{\mathbb{T}-\mathbb{D}}$ and $C_{N ;+}^{\mathbb{T}-\mathbb{D}}=q C_{-}^{\mathbb{T}-\mathbb{D}}$ by the second relation in (5.13). Applying the first relation in (5.13), we obtain

$$
\begin{aligned}
C_{+}^{\mathbb{T}-\mathbb{D}}=C_{0 ;+}^{\mathbb{T}-\mathbb{D}} & =C_{1 ;+}^{\mathbb{T}-\mathbb{D}}+\left(t^{-1 / 2}-t^{1 / 2}\right) Z_{1}^{\mathbb{T}-\mathbb{D}} \\
& =C_{2 ;+}^{\mathbb{T}-\mathbb{D}}+\left(t^{-1 / 2}-t^{1 / 2}\right)\left(Z_{1}^{\mathbb{T}-\mathbb{D}}+Z_{2}^{\mathbb{T}-\mathbb{D}}\right) \\
& =\cdots \\
& =q C_{-}^{\mathbb{T}-\mathbb{D}}+\left(t^{-1 / 2}-t^{1 / 2}\right)\left(Z_{1}^{\mathbb{T}-\mathbb{D}}+Z_{2}^{\mathbb{T}-\mathbb{D}}+\cdots+Z_{N}^{\mathbb{T}-\mathbb{D}}\right) .
\end{aligned}
$$

Each tangle $Z_{i}^{\mathbb{T}-\mathbb{D}}$ is isotopic to a braid (also denoted $Z_{i}^{\mathbb{T}-\mathbb{D}}$ ). The braid $Z_{1}^{\mathbb{T}-\mathbb{D}}$ is obtained as a product of:

- $Y_{1}$ for each $U$ step of $\mathcal{P}_{C}$;
- $Y_{1} X_{1} Y_{1}^{-1}$ for each $R$ step of $\mathcal{P}_{C}$.

For $i=1,2, \ldots, N$, let $Z_{i} \in \ddot{\mathbf{H}}_{N ; q, t}$ be the image of the braid $Z_{i}^{\mathbb{T}-\mathbb{D}} \in \mathrm{BSk}_{N ; q, t}(\mathbb{T}, *)$ under the map (5.14). We see that $Z_{i}=T_{i-1}^{-1} \cdots T_{2}^{-1} T_{1}^{-1} Z_{1} T_{1}^{-1} T_{2}^{-1} \cdots T_{i-1}^{-1}$. Projecting to $\mathbf{S} \ddot{H}_{N ; q, t}$ and applying (2.9), we find $\boldsymbol{e}_{N} Z_{i} \boldsymbol{e}_{N}=t^{i} \boldsymbol{e}_{N} Z_{1} \boldsymbol{e}_{N}$. Comparing the above description of $Z_{1}^{\mathbb{T}-\mathbb{D}}$ to Definition 1.3, we find $D_{C}^{(N)}=\gamma_{N ; t} \boldsymbol{e}_{N} Z_{1} \boldsymbol{e}_{N}$. Summarizing, the image of $C_{+}^{\mathbb{T}-\mathbb{D}}-q C_{-}^{\mathbb{T}-\mathbb{D}}$ in $\mathrm{S} \ddot{\mathrm{H}}_{N ; q, t}$ under the composition 5.17 ) is given by

$$
\frac{\left(t^{-1 / 2}-t^{1 / 2}\right)}{\gamma_{N ; t}}\left(1+t+\cdots+t^{N-1}\right) D_{C}^{(N)}=t^{-1 / 2} D_{C}^{(N)}
$$

Thus, the image of $C^{\mathbb{T}-\mathbb{D}}$ under (5.17) is indeed given by 1.6 when $C$ is primitive. The case of arbitrary $C$ follows by (1.3) and (1.8).

Remark 5.12. The recurrence (2.11) may be represented diagrammatically; see e.g. EH19, Equation (1.2)]. Similarly, our proof of the skein relation (1.9) given in Section 5 may be interpreted as shown in Figure 9. Given that (2.11) admits a lift to the level of Rouquier complexes computing KR homology Hog18, EH19, Mel22], it is natural to expect that our


Figure 10. An expanded version of Figure 1. Here, $C$ is a curve from $(0,0)$ to ( $m, n$ ) with $k:=\mathrm{k}(C)$ lattice segments.
skein relation admits a similar lift to KR homology or, perhaps, to some other (yet to be constructed) homology theory associating a symmetric function to a link in a punctured torus.

## 6. A commutative diagram

In this section, we explore the commutative diagram in Figure 10, which is an expanded version of the diagram in Figure 1. The maps between the various algebras and modules are shown on the left, and the images of a curve $C$ under these maps are shown on the right. For each of the squares A, B1, B2, C1, C2, we will discuss the maps involved and check that the square commutes. Throughout this section, we let $C_{\boldsymbol{x}}$ be an almost linear curve from $(0,0)$ to $\boldsymbol{x}:=(m, n)$. We set $d:=\operatorname{gcd}(m, n), \boldsymbol{x}_{0}:=\frac{1}{d} \boldsymbol{x}$, and recall that $\delta_{q, t}:=\frac{1}{t^{1 / 2}(1-q)}$; cf. (1.6). In particular, $\delta_{q, q^{-1}}=\frac{1}{q^{-1 / 2}-q^{1 / 2}}$.
6.1. Square A. By Theorem 1.5, for any curve $C$, the image of $C^{\mathbb{T}-\mathbb{D}}$ under (5.17) is $\delta_{q, t}^{\mathrm{k}(C)} D_{C}^{(N)}$, and by Theorem 1.6, its limit under $N \rightarrow \infty$ is $\delta_{q, t}^{\mathrm{k}(C)} D_{C}$. We now check that the isomorphism $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{T}) \xrightarrow{\sim} \mathcal{E}_{q, q^{-1}}^{+}$constructed in MS17] sends $\left.C^{\mathbb{T}} \mapsto \delta_{q, t}^{\mathrm{k}(C)} D_{C}\right|_{t=q^{-1}}$.

Notation 6.1. Our notation is obtained from that of MS17] via ${ }^{8}$

$$
\begin{equation*}
\left(q, t, s, v, P_{\boldsymbol{x}}\right) \mapsto\left(q^{-1}, t, t^{1 / 2}, v, W_{\boldsymbol{x} ; q}^{\mathbb{T}}\right) . \tag{6.1}
\end{equation*}
$$

We claim that the isomorphism of [MS17, Theorem 5.6] is given by

$$
\begin{equation*}
\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{T}) \xrightarrow{\sim} \mathcal{E}_{q, q^{-1}}^{+}, \quad W_{k \boldsymbol{x}_{0} ; q}^{\mathbb{T}} \mapsto-\left.q^{-k / 2} P_{k \boldsymbol{x}_{0}}^{\mathcal{E}}\right|_{t=q^{-1}} \tag{6.2}
\end{equation*}
$$

Indeed, in the notation of MS17, Theorem 5.6], the isomorphism $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{T}) \xrightarrow{\sim} \mathcal{E}_{q, q^{-1}}^{+}$sends $P_{\boldsymbol{x}} \mapsto\left(q^{\mathrm{d}(\boldsymbol{x}) / 2}-q^{-\mathrm{d}(\boldsymbol{x}) / 2}\right) u_{\boldsymbol{x}}$. Converting this to our notation and applying (3.7), we obtain (6.2).

[^6]

Figure 11. For an almost linear curve $C$ from $(0,0)$ to $(2,2), C_{+}^{\mathbb{T}-\mathbb{D}}$ is a $\sigma_{1^{-}}$ decoration of a curve $C_{(1,1)}$ in $\mathbb{T}-\mathbb{D}$ of homology class $(1,1)$ while $C_{-}^{\mathbb{T}-\mathbb{D}}$ is not. The shaded ellipse represents the puncture $\mathbb{D}$ in $\mathbb{T}-\mathbb{D}$.

The element $C_{\boldsymbol{x}}^{\mathbb{T}}$ is obtained by taking a straight line segment $C_{\boldsymbol{x}_{0}}$ from $(0,0)$ to $\boldsymbol{x}_{0}$ and decorating $C_{\boldsymbol{x}_{0}}^{\mathbb{T}}$ by the Coxeter braid $\sigma_{1} \sigma_{2} \cdots \sigma_{d-1} .9$ By Notation 5.3 and [GW23, Proposition 2.6], we have

$$
\operatorname{Tr}_{\Lambda_{q}}\left(T_{1}^{-1} T_{2}^{-1} \cdots T_{d-1}^{-1}\right)=\frac{(-1)^{d-1}}{q^{1 / 2}-q^{-1 / 2}} e_{d}\left[\mathbf{X}\left(q^{1 / 2}-q^{-1 / 2}\right)\right] .
$$

Embedding $\mathbb{A}$ into a small ribbon neighborhood of $C_{\boldsymbol{x}_{0}}$ and applying (5.10), we obtain a homomorphism $\mathrm{Sk}_{q^{-1}}(\mathbb{A}) \rightarrow \mathrm{Sk}_{q^{-1}}(\mathbb{T})$. Combining this with Proposition 5.5, we obtain the following result.

Corollary 6.2. The element $C_{\boldsymbol{x}}^{\mathbb{T}}$ is expressed in $\left(W_{k x_{0} ; q}^{\mathbb{T}}\right)_{k \geq 0}$ with the same coefficients as $\frac{(-1)^{d-1}}{q^{1 / 2}-q^{-1 / 2}} e_{d}\left[\mathbf{X}\left(q^{1 / 2}-q^{-1 / 2}\right)\right]$ is expressed in $\left(p_{k}\right)_{k \geq 0}$.

By [MS21, Theorem 5.7], the map (5.17) sends $W_{k \boldsymbol{x}_{0} ; t^{-1}}^{\mathbb{T}-\mathbb{D}} \mapsto \frac{t^{k / 2}-t^{-k / 2}}{q^{k}-1} P_{k x_{0}}^{\mathcal{E}}$. For $t=q^{-1}$, this recovers the isomorphism (6.2) of [MS17]; see also [MS21, Remark 2.5]. Recall that the substitution $p_{k} \mapsto-q^{-k / 2} p_{k}$ corresponds to the plethystic substitution $\Lambda_{q} \rightarrow \Lambda_{q}, F \mapsto$ $F\left[-q^{-1 / 2} \mathbf{X}\right]$. We obtain the following.
Corollary 6.3. The image of $C_{\boldsymbol{x}}^{\mathbb{T}}$ under (6.2) is expressed in $\left(P_{k \boldsymbol{x}_{0}}^{\mathcal{E}}\right)_{k \geq 0}$ with the same coefficients as $\frac{(-1)^{d-1}}{q^{1 / 2}-q^{-1 / 2}} e_{d}\left[\mathbf{X}\left(q^{-1}-1\right)\right]$ is expressed in $\left(p_{k}\right)_{k \geq 0}$.
Proposition 6.4. Square A in Figure 10 is commutative.
Proof. Recall that by Theorems 1.5 and 1.6 , the image of $C_{\boldsymbol{x}}^{\mathbb{T}-\mathbb{D}}$ in $\mathcal{E}_{q, t}^{+}$is given by $\delta_{q, t} D_{\boldsymbol{x}}$. Substituting $t=q^{-1}$ into Corollary 4.4, we see that $\left.\delta_{q, t} D_{\boldsymbol{x}}\right|_{t=q^{-1}}=\left.\frac{1}{q^{-1 / 2}-q^{1 / 2}} D_{\boldsymbol{x}}\right|_{t=q^{-1}}$ is expressed in $\left(P_{k, 0}^{\mathcal{E}}\right)_{k \geq 0}$ with the same coefficients as $\frac{\left(-q^{-1}\right)^{d}}{q^{-1 / 2}-q^{1 / 2}} e_{d}[\mathbf{X}(1-q)]$ is expressed in $\left(p_{k}\right)_{k \geq 0}$. Since these coefficients agree with those in Corollary 6.3, it follows that the image of $C_{\boldsymbol{x}}^{\mathbb{T}}$ under (6.2) agrees with the $t=q^{-1}$-specialization of the image of $C_{\boldsymbol{x}}^{\mathbb{T}-\mathbb{D}}$ under (5.17). In other words, square A in Figure 10 is commutative for almost linear curves.

Since all maps involved respect multiplication, we see that square A commutes for piecewise almost linear curves. We now check that the map (6.2) also respects the skein relation 1.9). (This is clear for all other maps involved in square A.) Substituting

[^7]

Figure 12. Computing the braid $\beta_{C}^{\mathbb{A}}$ associated to a curve $C$; see Definition 6.5.
$D_{C}^{(N)} \mapsto \delta_{q, t}^{-\mathrm{k}(C)} C^{\mathbb{T}}$ (cf. 1.6) into the skein relation (1.9) and letting $t=q^{-1}$, we arrive at the identity

$$
\begin{equation*}
C_{+}^{\mathbb{T}}=C_{-}^{\mathbb{T}}+\left(q^{-1 / 2}-q^{1 / 2}\right) C_{0}^{\mathbb{T}} \tag{6.3}
\end{equation*}
$$

for $C_{+}, C_{-}, C_{0}$ as in Theorem 1.7. This agrees with (5.1) since $C_{+}$contains a positive crossing $\nless$ where $C_{-}$contains a negative crossing $\lambda$. Thus, 6.3 indeed holds inside $\mathrm{Sk}_{q^{-1}}(\mathbb{T})$, which by Remark 1.10 implies that square $A$ in Figure 10 is commutative for arbitrary curves.
6.2. Squares B1 and B2. Recall from Definition 5.7 that the vertical map $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{T}) \rightarrow$ $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A})$ consists of first applying an automorphism $\psi_{v}$ of $\mathrm{Sk}_{q^{-1}}^{+}(\mathbb{T})$ sending $C^{\mathbb{T}} \mapsto v^{n} C^{\mathbb{T}}$ and then inserting a solid torus inside $\mathbb{T}$ as shown in Figure 6 .

Definition 6.5. Let $C$ be a curve from $(0,0)$ to $(m, n)$. Consider the link $L_{C}$ whose link diagram is drawn on $\mathbb{T}$ as in Section 1.2. For each $x \in[0,1]$ such that the point $(x, 1)$ (equivalently, $(x, 0)$ ) belongs to the link diagram of $L_{C}$, draw a vertical line segment from $(x, 1)$ to $(x, 0)$ passing above all other strands of $L_{C}$. The result is a planar link diagram drawn on $\mathbb{A}$, where the link is obtained as the annular closure of an $m$-strand braid denoted $\beta_{C}^{\mathbb{A}}$. We let $T_{C}^{\mathbb{A}} \in \mathbf{H}_{m ; q^{-1}}$ be the image of $\beta_{C}^{\mathbb{A}}$ under the standard homomorphism $\mathcal{B}_{m} \rightarrow$ $\mathbf{H}_{m ; q^{-1}}$, and let $C^{\mathbb{A}} \in \mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A})$ be the image of $T_{C}^{\mathbb{A}}$ under the identification (5.7). See Figure 12.

Remark 6.6. The "wrapping" procedure described in Definition 5.7 produces a framed link $L_{C}^{\prime}$ which coincides with $L_{C}$ (with blackboard framing) except that the framing of $L_{C}^{\prime}$ contains $n$ extra full twists. This discrepancy is accounted for by the application of the automorphism $\psi_{v}$ in Definition 5.7.

The horizontal map $\phi_{\mathbb{A}}: \mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A}) \xrightarrow{\sim} \Lambda_{q}$ is then defined as follows. For a braid $\beta \in \mathcal{B}_{m}$, we set

$$
\begin{equation*}
\phi_{\mathbb{A}}(\hat{\beta}):=\left(-q^{1 / 2}\right)^{-m} \omega \operatorname{Tr}_{\Lambda_{q}}\left(T_{\beta}\right), \tag{6.4}
\end{equation*}
$$

where $\omega$ is the omega involution [Sta99, Section 7.6]. It is clear that $\phi_{\mathbb{A}}$ is an algebra homomorphism.
Proposition 6.7. Squares B1 and B2 in Figure 10 are commutative.

Proof. The result is obvious for B2. To check the commutativity of B1, we need to show that for any curve $C$ from $(0,0)$ to $(m, n)$, we have

$$
\begin{equation*}
\left.\left(q^{-1 / 2}-q^{1 / 2}\right)^{-\mathrm{k}(C)} D_{C} \cdot 1\right|_{t=q^{-1}}=\left(-q^{1 / 2}\right)^{-m} \omega \operatorname{Tr}_{\Lambda_{q}}\left(T_{C}^{\mathbb{A}}\right) . \tag{6.5}
\end{equation*}
$$

This may be deduced from [MS17, Proposition 7.17] after matching our conventions to theirs; see also (6.1) and MS17, Section 7.1.1 and Equation (7.7)].
Example 6.8. Consider the three curves in Figure 3. We compute the left-hand side of (6.5) using (4.2)-(4.4). For the right-hand side, we first use Figure 12 to find $T_{C_{+}}^{\mathbb{A}}=T_{1}^{-3}, T_{C_{-}}^{\mathrm{A}}=$ $T_{1}^{-1}, T_{C_{0}}^{\mathrm{A}}=T_{1}^{-2}$, and then apply (5.9). We calculate that for $C=C_{+}, C_{-}, C_{0}$, both sides of (6.5) are given by $q^{-\frac{5}{2}} s_{11}-q^{\frac{1}{2}} s_{2}, q^{-\frac{3}{2}} s_{11}-q^{-\frac{1}{2}} s_{2}, q^{-2} s_{11}+s_{2}$, respectively.
6.3. Squares C 1 and C 2 . Before discussing the maps in squares C 1 and C 2 , we revisit the symmetric function $F_{C}$ introduced in (1.10). By definition, $F_{C}$ is obtained from $\delta_{q, t}^{\mathrm{k}(C)} D_{C} \cdot 1$ via the map $F \mapsto \delta_{q, t}^{-\mathrm{k}(C)} F\left[\frac{\mathbf{X}}{1-t}\right]$. Specializing $t=q^{-1}$ and applying (6.5), we get

$$
\begin{equation*}
\left.F_{C}\right|_{t=q^{-1}}=\left(q^{-1 / 2}-q^{1 / 2}\right)^{\mathrm{k}(C)} \operatorname{Tr}_{\Lambda_{q}}\left(T_{C}^{\mathbb{A}}\right)\left[\frac{\mathbf{X}}{q^{-1 / 2}-q^{1 / 2}}\right] . \tag{6.6}
\end{equation*}
$$

Next, let the right vertical map in square C 2 be given by

$$
\begin{equation*}
\Lambda_{q, t} \rightarrow \mathbb{C}\left(a, q^{1 / 2}, t^{1 / 2}\right), \quad F \mapsto F\left[\frac{a-a^{-1}}{1-t}\right] \tag{6.7}
\end{equation*}
$$

Specializing $t=q^{-1}$, we define the left vertical map in square C 2 by

$$
\begin{equation*}
\Lambda_{q} \rightarrow \mathbb{C}\left(a, q^{1 / 2}\right), \quad F \mapsto F\left[\frac{a-a^{-1}}{1-q^{-1}}\right] \tag{6.8}
\end{equation*}
$$

The left vertical map in square C 1 is given by (5.11).
Recall the braid $\beta_{C}^{\mathbb{A}}$ from Definition 6.5. Our goal is to compute the writhe $\mathrm{w}(C)$ of $\beta_{C}^{\mathbb{A}}$, defined as the sum of exponents $e_{1}+e_{2}+\cdots+e_{t}$ of the expression $\beta_{C}^{\mathbb{A}}=\sigma_{i_{1}}^{e_{1}} \sigma_{i_{2}}^{e_{2}} \cdots \sigma_{i_{t}}^{e_{t}}$ of $\beta_{C}^{\mathbb{A}}$ in terms of the standard generators of $\mathcal{B}_{m}$.
Proposition 6.9. For a curve $C$ from $(0,0)$ to $(m, n)$,

$$
\begin{equation*}
\mathrm{w}(C)=(\mathrm{k}(C)-1)+(m-1)+2 \mathrm{~b}(C), \tag{6.9}
\end{equation*}
$$

where $\mathrm{b}(C)$ is the number of lattice points in $[1, m-1] \times[1, n-1]$ strictly below $C$.
Proof. The result is readily checked by induction on $\mathrm{b}(C)$. For the induction base, when $\mathrm{b}(C)=0$ and $C$ is primitive, we have $\beta_{C}^{\mathbb{A}}=\sigma_{1} \sigma_{2} \cdots \sigma_{m-1}$. Next, suppose that $C_{+}, C_{-}, C_{0}$ are three curves passing above, below, and through some lattice point $\boldsymbol{p}$ as in Theorem 1.7. The associated braids satisfy $\mathrm{w}\left(\beta_{C_{+}}^{\mathbb{A}}\right)-1=\mathrm{w}\left(\beta_{C_{0}}^{\mathbb{A}}\right)=\mathrm{w}\left(\beta_{C_{-}}^{\mathbb{A}}\right)+1$. Thus, if 6.9) holds for $C_{-}$then it holds for $C_{0}$ and $C_{+}$, which gives the induction step.
Proposition 6.10. Squares C1 and C 2 in Figure 10 are commutative.
Proof. Square C 2 commutes by construction. The fact that square C 1 commutes follows by combining (5.3), 6.9), and [GW23, Proposition 2.3(b)].
Proof of Proposition 1.19. This follows from the commutative diagram Figure 10. The lefthand side of $(1.15)$ is the image of $\delta_{q, t}^{k} \mathcal{P}_{C}^{\mathcal{E}}(a, q, t)$ under the bottom horizontal map $\left(t=q^{-1}\right)$ in square C 2 .

## 7. Comparisons and specializations

In this section, we view the EHA element $D_{C}$ as an operator on symmetric functions. We first recall the formalism of plethysm. If $A$ is an expression in terms of some variables, we define $p_{k}[A]$ to be the result of substituting $a^{k}$ for each variable $a$, and define $f[A]$ for any $f \in \Lambda$ by extending $p_{k} \mapsto p_{k}[A]$ to an algebra homomorphism $f \mapsto f[A]$. Note that the symbols $q, t$ also count as variables. By convention, the plethysm $f[\mathbf{X}]$ is obtained by taking $\mathbf{X}=x_{1}+x_{2}+\cdots$. Let $\phi: \Lambda_{q, t} \rightarrow \Lambda_{q, t}$ be the automorphism of symmetric functions given by the plethysm $f \mapsto f\left[\frac{\mathbf{X}}{1-t}\right]$, and recall the involution $\omega: \Lambda_{q, t} \rightarrow \Lambda_{q, t}$.

For a monotone curve $C$, let $\tilde{D}_{C}:=\phi \circ D_{C} \circ \phi^{-1}$ denote the symmetric function operator obtained by conjugating $D_{C}$ by $\phi$. Thus by definition $F_{C}=\tilde{D}_{C} \cdot 1$.
7.1. Shuffle conjectures. Let $C$ be the almost linear curve from $(0,0)$ to $(m, n)$; then $L_{C}$ is the $(m, n)$-almost torus knot. The associated operator $\tilde{D}_{m, n}$ is well studied, going back to GN15] (and Che13, AS15]) for the case $\operatorname{gcd}(m, n)=1$ of a torus knot. In particular, the (compositional) rational shuffle conjecture [BGLX15, Mel16] gives a positive, combinatorial expression for $\tilde{D}_{m, n} \cdot 1$ :

$$
\begin{equation*}
\omega\left(\tilde{D}_{m, n} \cdot 1\right)=\sum_{\pi \in \operatorname{Park}_{n, m}} t^{\operatorname{area}(\pi)} q^{\operatorname{dinv}(\pi)} F_{\operatorname{ides}(\pi)} \tag{7.1}
\end{equation*}
$$

Here, Park $_{n, m}$ denotes a certain set of parking functions, and $F_{\text {ides }(\pi)}$ denotes a fundamental quasisymmetric function. We refer the reader to [BGLX15] for definitions of area, dinv, ides.
7.1.1. The original shuffle conjecture $\mathrm{HHL}^{+} 05$ proved in CM18] is a combinatorial expression for the symmetric function $\nabla e_{n}$. The operator $\nabla$ of [BG99] can be interpreted in terms of the $\mathrm{SL}_{2}(\mathbb{Z})$-action on $\mathcal{E}_{q, t}$ as the following identity of operators on $\Lambda_{q, t}$ :

$$
\phi \circ u_{m, m+n} \circ \phi^{-1}=(\omega \circ \nabla \circ \omega)\left(\phi \circ u_{m, n} \circ \phi^{-1}\right)(\omega \circ \nabla \circ \omega)^{-1} .
$$

7.1.2. Up to a transformation $t \mapsto t^{-1}$, and a factor of $(1-t)$ (see 2.28$)$ ), our $D_{m, n}$ is equal to the element $P_{m, n}$ defined as a limit in [GN15, Section 3] of the elements $P_{m, n}^{N}$ below GN15, Definition 2.5].

Remark 7.1. On the other hand, for an almost linear curve $C$ from $(0,0)$ to $(n, n+1)$, we have $F_{C}=\tilde{D}_{n, n+1} \cdot 1=\omega\left(\nabla e_{n}\right)$, in contrast to [GN15, Corollary 6.5], where $\nabla e_{n}$ is obtained. This discrepancy appears to arise due to the use of [GN15, Proposition 2.3], which differs from our symmetric function actions by the automorphism $\omega$. For instance, according to [GN15, Proposition 6.4 and Corollary 6.5], we have $\tilde{P}_{0,1} \cdot p_{n}=\tilde{P}_{n, 1} \cdot 1=e_{n}$. We believe that one should instead have $\tilde{P}_{0,1} \cdot p_{n}=\frac{q^{n}-1}{1-t^{-1}} h_{n}$ and $\tilde{P}_{n, 1} \cdot 1=\frac{1}{1-t^{-1}} h_{n}$ in the notation of GN15; see [GN15, Equations (20) and (31)]. The factor $q^{n}-1$ appears to be missing from GN15, Equation (22)].
7.1.3. The symmetric function operators $\mathbf{Q}_{n, m}: \Lambda_{q, t} \rightarrow \Lambda_{q, t}$ appearing in the shuffle conjectures of [BGLX15] are related to ours by

$$
\begin{equation*}
\tilde{D}_{m, n}=(-1)^{m+\operatorname{gcd}(m, n)} \omega \circ \mathbf{Q}_{n, m} \circ \omega . \tag{7.2}
\end{equation*}
$$

Thus, (7.1) is a rephrasing of [BGLX15, Conjecture 3.1].
7.1.4. We give an explicit description of the operator $\tilde{D}_{m, 1}$. Set $M:=(1-t)(1-q)$. Following [ $\left.\mathrm{BHM}^{+} 21\right]$, define $\mathbf{D}_{k}, k \in \mathbb{Z}$ by the identity

$$
\begin{equation*}
\sum_{k \in \mathbb{Z}}(-z)^{-k} \mathbf{D}_{k}:=\Omega\left[-z^{-1} \mathbf{X}\right]^{\bullet} \Omega[z M \mathbf{X}]^{\perp} \tag{7.3}
\end{equation*}
$$

where for $f \in \Lambda$, we denote by $f^{\bullet}$ the multiplication operator by $f$, and by $f^{\perp}$ the adjoint operator to $f \bullet$ for the Hall inner product ${ }^{10}$ The following equality of symmetric function operators is a special case of (7.2):

$$
\begin{equation*}
\tilde{D}_{m, 1}=\omega \circ \mathbf{D}_{m} \circ \omega . \tag{7.4}
\end{equation*}
$$

7.2. Positroid links. In GL20, we introduced positroid links $L_{f}$ associated to positroid varieties in the Grassmannian, or to bounded affine permutations. In GL21, we studied repetition-free positroids, which led us to the study of convex curves. The following result follows from [GL22, Section 2.1] where concave curves were used instead. Specifically, the curves of [GL21, GL22] are related to our curves by a $180^{\circ}$-rotation, and the associated links $L_{C}$ coincide. Note that in Definition 6.5, the vertical line segments are drawn above all other strands, while they are drawn below all other strands in GL21, GL22] (see e.g. GL22, Figure 1(d)]).
Proposition 7.2. Let $C$ be a convex monotone curve, possibly passing through some lattice points. Then $L_{C}$ is a positroid link.

The positroid knots appearing in Proposition 7.2 coincide with the positroid knots associated to repetition-free permutations of [GL21]. Outside of the convex class, we do not know the answer to the following question.
Question 7.3. Which monotone links are isotopic to positroid links?
For example, the monotone curve Figure 4(c) is not convex, however, it coincides with the positroid knot discussed in [GL20, Example 4.21]. See Example A. 2 for further discussion.
7.3. Coxeter links. We relate our monotone links to the Coxeter links introduced in [OR17]. Consider a pair $(\boldsymbol{b}, \boldsymbol{\epsilon})$, where $\boldsymbol{b}=\left(b_{1}, b_{2}, \ldots, b_{m}\right)$ is a sequence of nonnegative integers and $\boldsymbol{\epsilon}=\left(\epsilon_{1}, \epsilon_{2}, \ldots, \epsilon_{m-1}\right)$ is a 0,1 -sequence.

Let $\operatorname{cox}(\boldsymbol{\epsilon}):=\sigma_{1}^{\epsilon_{1}} \sigma_{2}^{\epsilon_{2}} \cdots \sigma_{m-1}^{\epsilon_{m-1}}$ be the quasi-Coxeter braid associated to $\boldsymbol{\epsilon}$; cf. Notation 5.3 . For $i=1,2, \ldots, m$, let $\ell_{i}:=\sigma_{i-1} \cdots \sigma_{1} \sigma_{1} \cdots \sigma_{i-1}$ be a Jucys-Murphy element. By convention, $\ell_{1}$ is the identity braid. Finally, define

$$
\begin{equation*}
\beta_{b, \boldsymbol{\epsilon}}^{\operatorname{cox}}:=\ell_{1}^{b_{1}} \ell_{2}^{b_{2}} \cdots \ell_{m}^{b_{m}} \operatorname{cox}(\boldsymbol{\epsilon}) \tag{7.5}
\end{equation*}
$$

Braids of the form (7.5) are called Coxeter braids, and their annular closures are called Coxeter links.

Let $C$ be a curve from $(0,0)$ to $(m, n)$. For $i=0,1, \ldots, m$, let $\lambda_{i}$ be the maximal integer such that the point $\left(m-i, \lambda_{i}\right)$ is weakly below $C$. (In particular, $\lambda_{0}=n$.) For $i=1,2, \ldots, m$, set $b_{i}:=\lambda_{i-1}-\lambda_{i}$ and let $\boldsymbol{b}_{C}:=\left(b_{1}, b_{2}, \ldots, b_{m}\right)$ be the resulting sequence of nonnegative integers. We also let $S_{C}$ be the set of $i \in\{1,2, \ldots, m-1\}$ such that $C$ passes through a lattice point $(m-i, j)$ for some $j \in \mathbb{Z}$. Let $\boldsymbol{\epsilon}_{C}:=\left(\epsilon_{1}, \epsilon_{2}, \ldots, \epsilon_{m-1}\right)$ be given by $\epsilon_{i}:=1$ if $i \notin S_{C}$ and $\epsilon_{i}:=0$ otherwise.

We set $\operatorname{cox}(C):=\operatorname{cox}\left(\boldsymbol{\epsilon}_{C}\right)$ and $\beta_{C}^{\text {cox }}:=\beta_{b_{C}, \boldsymbol{\epsilon}_{C}}^{\text {cox }}$.

[^8]

Figure 13. From monotone links to Coxeter links.
Example 7.4. For the curve $C$ in Figure 13(a), we have $\left(\lambda_{0}, \lambda_{1}, \ldots, \lambda_{m}\right)=(4,3,3,2,0)$, $\boldsymbol{b}_{C}=(1,0,1,2), S_{C}=\{3\}$, and $\boldsymbol{\epsilon}_{C}=(1,1,0)$.

Proposition 7.5. The braid $\beta_{C}^{\text {cox }}$ is conjugate to the braid $\beta_{C}^{\mathbb{A}}$ constructed in Definition 6.5. In particular, any monotone link, when viewed as a link in $\mathbb{A} \times[0,1]$, is a Coxeter link, and any Coxeter link can be obtained in this way.
Proof. This result was shown for primitive monotone curves in GL22, Section 4.4]. We briefly reproduce the argument here, extending it to arbitrary curves. Let $C=\left[C_{1} C_{2} \ldots C_{k}\right]$ be a monotone curve from $(0,0)$ to $(m, n)$. The map $C \mapsto C^{\mathbb{T}}$ described in Sections 1.2 and 1.3 may be extended from monotone curves to curves from $(0,0)$ to $(m, n)$ whose first coordinate is strictly monotone increasing (dropping the monotonicity assumption on the second coordinate). Let us call such curves $x$-monotone. It is easy to see that the map $C \mapsto C^{\mathbb{T}}$ is invariant under applying an isotopy $C_{i}(t), t \in[0,1]$, to each segment $C_{i}$ of $C$, such that the endpoints of $C_{i}(t)$ are fixed (i.e., do not depend on $t$ ) and for each $t, C_{i}(t)$ passes through no lattice points other than the endpoints; see also [GL22, Corollary 4.1]. Furthermore, we may shift each $C_{i}$ vertically by some vector $\left(0, y_{i}\right)$; the projected curve $\bar{C}_{i}$ will be shifted vertically; its diagram will be drawn above $\bar{C}_{j}$ for $j<i$ and below $\bar{C}_{j}$ for $j>i$, and thus such a vertical shift results in an isotopy inside $\mathbb{T}$.

Applying the above operations, we may transform each segment $C_{i}$ of $C$ into a "lattice path" segment $C_{i}^{\prime}$ as shown in Figure 13(b). Namely, let $\pi_{C} \in \mathfrak{S}_{N}$ be the permutation associated to the braid $\operatorname{cox}(C)$. For each $i=0,1, \ldots, m-1$, consider the part of $C$ connecting $\left(i, y_{i}\right)$ to $\left(i+1, y_{i+1}\right)$ for some $y_{i}<y_{i+1}$. Let $j_{i}:=\left\lfloor y_{i}\right\rfloor$ and $j_{i+1}:=\left\lfloor y_{i+1}\right\rfloor$. Let $\epsilon>0$ be small. Consider a new $x$-monotone curve passing through the following points:

- start at $\left(i, j_{i}+\frac{i+1}{m+1}\right)$;
- proceed horizontally to $\left(i+1-\frac{i+1}{m+1}-\epsilon, j_{i}+\frac{i+1}{m+1}\right)$;
- proceed (almost) vertically ${ }^{11}$ to $\left(i+1-\frac{i+1}{m+1}+\epsilon, j_{i+1}+\frac{i+1}{m+1}\right)$;
- proceed horizontally to $\left(i+1-\frac{1}{m+1}, j_{i+1}+\frac{i+1}{m+1}\right)$;
- end at $\left(i+1, j_{i+1}+\frac{\pi_{C}(i)+1}{m+1}\right)$.

Let $C^{\prime}$ be the union of these curves for $i=0,1, \ldots, m-1$. By the above discussion, the projected curves $C^{\mathbb{T}},\left(C^{\prime}\right)^{\mathbb{T}}$ are related by isotopy in $\mathbb{T}$; the curve $\left(C^{\prime}\right)^{\mathbb{T}}$ is shown in

[^9]Figure 13(c), Applying the map $\left(C^{\prime}\right)^{\mathbb{T}} \mapsto \beta_{C^{\prime}}^{\mathbb{A}}$ from Definition 6.5, we obtain the braid $\beta_{C^{\prime}}^{\mathbb{A}}=\beta_{C}^{\text {cox }}$; see Figure $13(\mathrm{~d})$. Thus, the braids $\beta_{C}^{\mathbb{A}}$ and $\beta_{C}^{\text {cox }}$ are conjugate.
7.4. Shuffle algebra. We relate the operators $\tilde{D}_{C}$ to variants of Negut's shuffle algebra elements. Let $S$ denote the shuffle algebra, which we consider a subspace of $\mathbb{Q}(q, t)\left[x_{1}^{ \pm 1}, x_{2}^{ \pm 1}, \ldots\right]$, endowed with a noncommutative "shuffle product", and an isomorphism of algebras $\psi: S \rightarrow$ $\mathcal{E}_{q, t}^{+}$; see [SV13]. The precise description of $S$ will not be important for us since we are only interested in certain distinguished elements. The shuffle algebra has an action on $\Lambda_{q, t}$ compatible with $\psi$ and the action of $\mathcal{E}_{q, t}^{+}$on $\Lambda_{q, t}$ discussed in Section 3.3, conjugated by the plethysm $\phi$. Under this action,

$$
x_{1}^{a_{1}} \cdots x_{k}^{a_{k}} \text { acts by } \mathbf{D}_{a_{1}} \cdots \mathbf{D}_{a_{k}}
$$

where $\mathbf{D}_{a}$ is defined in (7.3).
Let $(\boldsymbol{b}, \boldsymbol{\epsilon})$ be as in Section 7.3. Define the rational functions

$$
\eta_{\boldsymbol{b}, \boldsymbol{\epsilon}}^{\prime}=\frac{x_{1}^{b_{1}} \cdots x_{k}^{b_{m}}}{\prod_{i=2}^{m}\left(1-q t x_{i-1} / x_{i}\right)^{\epsilon_{i-1}}}
$$

The following result is a variant of Neg14, Proposition 6.2].
Proposition 7.6. There are elements $\eta_{\boldsymbol{b}, \boldsymbol{\epsilon}} \in S$ characterized by the equality

$$
\mathbf{H}_{q, t}\left(\eta_{\boldsymbol{b}, \boldsymbol{\epsilon}}\right)=\mathbf{H}_{q, t}\left(\eta_{\boldsymbol{b}, \boldsymbol{\epsilon}}^{\prime}\right) .
$$

where $\mathbf{H}_{q, t}$ denotes the $q, t$-symmetrization operator of $\left[\mathrm{BHM}^{+} 21\right.$, Equation (46)].
In particular, $\eta_{\boldsymbol{b}, \boldsymbol{\epsilon}}$ are Laurent polynomials.
The following skein relation is a generalization of the second displayed equation in [Neg14, Proof of Proposition 6.13].
Proposition 7.7. The skein relation holds for the elements $\eta_{\boldsymbol{b}, \boldsymbol{\epsilon}}$ :

$$
\eta_{b_{C_{+}}, \epsilon_{C_{+}}}=q t \eta_{b_{C_{-}}, \epsilon_{C_{-}}}+\eta_{b_{C_{0}}, \epsilon_{C_{0}}} .
$$

Proof. This follows from linearity of $\mathbf{H}_{q, t}$ and the equality

$$
\eta_{b_{C_{+}}, \epsilon_{C_{+}}}^{\prime}=q t \eta_{\boldsymbol{b}_{C_{-}}, \epsilon_{C_{-}}}^{\prime}+\eta_{b_{C_{0}}, \epsilon_{C_{0}}}^{\prime} .
$$

Proposition 7.8. For a curve $C$, we have the equality of symmetric function operators

$$
\begin{equation*}
\tilde{D}_{C}=\omega \circ \eta_{b_{C}, \epsilon_{C}} \circ \omega . \tag{7.6}
\end{equation*}
$$

Furthermore, we have (cf. $\left[\mathrm{BHM}^{+} 21\right.$, Equation (146)])

$$
F_{C}=\tilde{D}_{C} \cdot 1=\omega\left(D_{b_{C}, \epsilon_{C}} \cdot 1\right)=\mathbf{H}_{q, t}\left(\frac{x_{1}^{b_{1}} \cdots x_{k}^{b_{m}}}{\prod_{i=2}^{m}\left(1-q t x_{i-1} / x_{i}\right)^{\varepsilon_{i-1}}}\right)_{\mathrm{pol}}
$$

where $(\cdots)_{\text {pol }}$ denotes the "polynomial part" operator, removing all Laurent monomials in $x_{i}$ that are not polynomials; see $\left[\mathrm{BHM}^{+} 21\right.$, Section 2.3].
Proof sketch. When $C$ is an almost linear curve, the result follows from the discussion in Section 7.1 and known relations between the shuffle algebra and $\mathcal{E}_{q, t}^{+}$; see Neg14, GN15. By Proposition 7.7 and (1.9) both sides of (7.6) satisfy the skein relation. Finally, both sides of the stated equality are compatible with composition of operators, or concatenation of monotone curves. It follows that (7.6) holds for all monotone curves.

The second statement follows from $\left[\mathrm{BHM}^{+}\right.$21, Proposition 3.5.2].

Remark 7.9. Proposition 7.8 implies that the operators $D_{b_{1}, \ldots, b_{l}}$ of [ $\left.\mathrm{BHM}^{+} 21\right]$ are special cases of our operators $\tilde{D}_{C}$.

Remark 7.10. In Neg14, Proposition 6.4], for each $(m, n)$, certain elements in the shuffle algebra, and thus the EHA, are constructed, depending on a binary string $\delta=\left(\delta_{1}, \ldots, \delta_{d-1}\right)$ where $d=\operatorname{gcd}(m, n)$. Let $C_{\delta}$ be the primitive monotone curve from $(0,0)$ to $(m, n)$, staying close to the diagonal, and passing above or below a diagonal lattice point depending on whether $\delta_{i}=0$ or 1 . Then the image of Neguts's $X^{\delta}$ in $\mathcal{E}_{q, t}$ coincides with our operator $D_{C_{\delta}}$. Specifically, for $(m, n)=(d, 0)$, using $D_{C_{\delta}}^{(N)}$ instead of $D_{d, 0}^{(N)}$, we would obtain $s_{R_{\delta}}\left[\mathbf{X}\left(1-t^{-1}\right)\right]$ instead of $e_{d}\left[\mathbf{X}\left(1-t^{-1}\right)\right]$ in Proposition 2.11, where $R_{\delta}$ is a ribbon skew shape with $d$ boxes. Note however that the operators $D_{C_{\delta}}$ do not in general satisfy the positivity Conjecture 1.13 .
7.5. Magic formula. We state a slight generalization of the magic formula of Neg14, GN15 expressing the symmetric function $F_{C}$ as a sum over standard Young tableaux. We follow the exposition of GHSR20. We draw Young diagrams in French notation, so that the boxes are located in the nonnegative orthant with the bottom left box having coordinates $(1,1)$. Let $T$ be a standard Young tableau with $m$ boxes. For $i=1,2, \ldots, m$, we set $z_{i}:=z_{i}(T):=q^{c-1} t^{r-1}$, where the box of $T$ containing $i$ has coordinates $(r, c)$. For a $\{0,1\}$ sequence $\boldsymbol{\epsilon}=\left(\epsilon_{1}, \epsilon_{2}, \ldots, \epsilon_{m-1}\right)$ and a standard Young tableau $T$, we set

$$
\operatorname{wt}(T ; \boldsymbol{\epsilon}):=\prod_{i=2}^{m} \frac{1}{\left(1-z_{i}^{-1}\right)\left(1-q t z_{i-1} / z_{i}\right)^{\epsilon_{i-1}}} \prod_{i<j} \frac{\left(1-z_{i} / z_{j}\right)\left(1-q t z_{i} / z_{j}\right)}{\left(1-q z_{i} / z_{j}\right)\left(1-t z_{i} / z_{j}\right)},
$$

where the zero factors in the numerator and denominator are omitted by convention. Given a sequence $\boldsymbol{b}=\left(b_{1}, b_{2}, \ldots, b_{m}\right)$ of integers, introduce a symmetric function

$$
\begin{equation*}
F_{\boldsymbol{b}, \boldsymbol{\epsilon}}:=\sum_{T \in \mathrm{SYT}(m)} \mathrm{wt}(T ; \boldsymbol{\epsilon}) z_{1}^{b_{1}} z_{2}^{b_{2}} \cdots z_{m}^{b_{m}} \nabla^{-1} \tilde{H}_{\mathrm{sh}(T)}, \tag{7.7}
\end{equation*}
$$

where the summation is over all standard Young tableaux $T$ with $m$ boxes, $\operatorname{sh}(T)$ is the shape of $T, \tilde{H}_{\lambda}$ are the modified Macdonald polynomials, and $\nabla$ is the nabla operator of [BG99].

When $\boldsymbol{\epsilon}=(1,1, \ldots, 1)$, Equation (7.7) is obtained from GHSR20, Equation (3)] by inserting the term $\nabla^{-1} \tilde{H}_{\operatorname{sh}(T)}$. We thank E. Gorsky for suggesting this modification to us.

The proof of the following formula (also known as the magic formula; see [EH19]) may be obtained by adapting the methods in the proof of [GN15, Theorem 1.1].

Proposition 7.11. For any curve $C$, we have

$$
F_{C}=\omega F_{b_{C}, \epsilon_{C}}
$$

7.6. The specialization $t=1$. Let $\mathcal{P}$ denote an up-right lattice path from $(0,0)$ to $(m, n)$. We let area $(\mathcal{P})$ denote the number of unit squares within the rectangle and below $\mathcal{P}$. Recall that $\mathcal{P}_{C}$ denotes the highest lattice path staying weakly below a monotone curve $C$. Define $h_{\mathcal{P}}:=h_{a_{0}} h_{a_{1}} \cdots h_{a_{n}} \in \Lambda_{q, t}$, where the maximal horizontal portions of the path $\mathcal{P}$ are of sizes $a_{0}, a_{1}, \ldots, a_{n}$. Note that $h_{\mathcal{P}}$ always has degree $m$. The following result is a variant of $\left[\mathrm{BHM}^{+} 21\right.$, Equation (148)].

Proposition 7.12. For a monotone curve $C$, we have

$$
\begin{equation*}
\left.F_{C}\right|_{t=1}=\sum_{\mathcal{P}} q^{\operatorname{area}\left(\mathcal{P}_{C}\right)-\operatorname{area}(\mathcal{P})} h_{\mathcal{P}} \tag{7.8}
\end{equation*}
$$

summed over lattice paths $\mathcal{P}$ weakly below $C$, such that $\mathcal{P}$ passes through all the lattice points that $C$ passes through.

Proof. When $C$ is an almost linear curve, this follows from the shuffle conjecture (i.e., the right-hand side of (7.1)). More generally, when $C$ is a primitive monotone curve, the statement follows from $\mathrm{BHM}^{+} 21$, Equation (148)] and Remark 7.9 , after translating their notation into ours. Finally, it is straightforward to see that if 7.8) holds for two of the curves in (1.12), then the skein relation implies that it holds for the third. This proves (7.8) for all monotone curves by induction on the number of lattice points that $C$ passes through.
Remark 7.13. It follows from [KT22, Proposition 4.9] that $\left.\tilde{D}_{C}\right|_{t=1}$ acts on $\Lambda_{q, t}$ by multiplication by $\left.F_{C}\right|_{t=1}$. We thank Eugene Gorsky for pointing out this reference.

Corollary 7.14. The coefficient of $s_{m}$ in $\left.F_{C}\right|_{t=q=1}$ is equal to the number of lattice paths $\mathcal{P}$ weakly below $C$, such that $\mathcal{P}$ passes through all the lattice points that $C$ passes through.

In view of Conjecture 1.13, we have the following problem.
Problem 7.15. For a primitive $\mathbb{Z}$-convex curve $C$, find a statistic dinv on lattice paths so that the coefficient of $s_{m}$ in $F_{C}$ is given by

$$
\left\langle s_{m}, F_{C}\right\rangle=\sum_{\mathcal{P}} q^{\operatorname{area}\left(\mathcal{P}_{C}\right)-\operatorname{area}(\mathcal{P})} t^{\operatorname{dinv}(\mathcal{P})}
$$

summed over lattice paths $\mathcal{P}$ weakly below $C$.
7.7. The specialization $t=q^{-1}$. At $t=q^{-1}$, we do not have a combinatorial formula for $F_{C}$. However, we record the following consequence of Figure 10, giving the precise meaning of $F_{C}$ in terms of the skein of the annulus.
Proposition 7.16. Under the isomorphism $\phi_{\mathbb{A}}: \mathrm{Sk}_{q^{-1}}^{+}(\mathbb{A}) \xrightarrow{\sim} \Lambda_{q}$ defined in $(6.4)$, the image of $C^{\mathbb{A}}$ is equal to $\left.\left(q^{-1 / 2}-q^{1 / 2}\right)^{-\mathrm{k}(C)} F_{C}\right|_{t=q^{-1}}\left[\mathbf{X}\left(1-q^{-1}\right)\right]$.

## 8. $\mathbb{Z}$-CONVEX COAXIAL ALMOST TORUS LINKS ARE ALGEBRAIC

We shall use the language of iterated torus cables and splice diagrams, and refer the reader to EN85] for a thorough treatment. The $(m, n)$-torus cable of a knot $K$ (or of a component $K$ of a link $L$ ) in $\mathbb{R}^{3}$ is defined as follows. The boundary of a tubular neighborhood $N(K)$ of $K$ in $\mathbb{R}^{3}$ is a torus $S=\partial N(K)$. The topological longitude $L_{\text {top }}$ and meridian $M$ are the simple closed curves on $S$ characterized (up to isotopy) by the following relations (see EN85, p.21]):

$$
\begin{array}{rlrl}
M \sim 0 & \text { and } & L_{\text {top }} & \sim K \\
\operatorname{lk}(M, K) & =1 & \text { and } H_{1}(N(K)) ; \\
\operatorname{lk}\left(K, L_{\text {top }}\right) & =0, &
\end{array}
$$

where $\operatorname{lk}\left(A, A^{\prime}\right)$ denotes the linking number of the knots $A, A^{\prime}$. By definition, the $(m, n)$-cable of $K$ is obtained by replacing $K$ by the simple closed curve $\gamma$ on $S$ satisfying $\gamma \sim m L_{\text {top }}+n M$.

Let $(m, n)$ be a pair of positive integers and with $d=\operatorname{gcd}(m, n)$, we write $m=d p$ and $n=d q$. Let $T_{(m, n)}^{\prime}$ be the $(d, d p q+1)$-cable of the torus knot $T_{p, q}$. It has the splice diagram:


The $\oplus$ vertices are called nodes; the remaining vertices are called leaves. Roughly speaking, each node represents a 3-manifold, and each edge incident to a node represents a 2 -torus boundary component. An arrowhead leaf represents a component of a link, and the edge incident to it represents the 2-torus obtained as the boundary of its tubular neighborhood. A bulletpoint leaf represents a 2-torus boundary component that has been filled in with a solid torus.

Recall the definition of an almost torus knot from Remark 1.16 ,
Lemma 8.1. Let $C$ be an almost linear curve from $(0,0)$ to $(m, n)$. Then the $(m, n)$-almost torus knot $L_{C}$ is isotopic to the $k n o t T_{(m, n)}^{\prime}$.

Proof. Let $S=\partial N\left(T_{p, q}\right)$ denote the boundary of a tubular neighborhood of the torus knot $T_{p, q}$. Recall that we have defined curves $L_{\text {top }}$ and $M$ on $S$. Consider the torus $\mathbb{T}=\mathbb{R}^{2} / \mathbb{Z}^{2}$ equipped with a standard embedding $\mathbb{T} \hookrightarrow \mathbb{R}^{3}$. Viewing $T_{p, q} \subset \mathbb{T}$ as the projection of a straight line segment $C_{p, q}$ from $(0,0)$ to $(p, q)$, the projection of $C_{p, q}+(-\epsilon, \epsilon)$ can also be viewed as a longitude $L_{\text {alg }}$ on $S$, called the algebraic longitude. The linking number of $L_{\mathrm{alg}}$ and $S$ is given by $\operatorname{lk}\left(S, L_{\mathrm{alg}}\right)=p q$, and thus $L_{\mathrm{alg}} \sim L_{\mathrm{top}}+p q M$ (cf. EN85, Proof of Proposition 1A. 1 on p.52]). By definition, $T_{m, n}^{\prime}$ is (isotopic to) the simple closed curve on $S$ satisfying $T_{m, n}^{\prime} \sim d L_{\text {top }}+(d p q+1) M$.

Recall from Section 6.1 that $C$ is a $\sigma_{1} \sigma_{2} \cdots \sigma_{d-1}$-decoration of $C_{p, q}$. The annular closure of the braid $\sigma_{1} \sigma_{2} \cdots \sigma_{d-1}$ is a ( $d, 1$ )-torus knot, which we may view as embedded in $S$. Thus, the projection of $C$ to $S$ is isotopic to a curve on $S$ with homology class $C \sim d L_{\text {alg }}+M \sim$ $d L_{\text {top }}+(d p q+1) M$, as required.

Using Lemma 8.1, we can construct a splice diagram of $L_{C}$ for an arbitrary piecewise almost linear curve $C$. Let $\left(m_{1}, n_{1}\right), \ldots,\left(m_{r}, n_{r}\right)$ be a sequence of pairs of positive integers. Let $\mathbb{T}_{1}, \mathbb{T}_{2}, \ldots, \mathbb{T}_{r}$ be tori in $\mathbb{R}^{3}$ with the same central circle $S^{1}$, and strictly decreasing radii. Place the almost torus knot $T_{\left(m_{i}, n_{i}\right)}$ on $\mathbb{T}_{i}$. The coaxial almost torus link $T_{\left(m_{1}, n_{1}\right), \ldots,\left(m_{r}, n_{r}\right)}$ is the $r$-component link in $\mathbb{R}^{3}$ obtained as the union of all these almost torus knots. In particular, if $\operatorname{gcd}(p, q)=1$, the $r$-component link $T_{(p, q), \ldots,(p, q)}$ is the torus link $T_{r p, r q}$. Note that if $m_{i} / n_{i}=m_{i+1} / n_{i+1}$ then swapping the order of $\left(m_{i}, n_{i}\right)$ and $\left(m_{i+1}, n_{i+1}\right)$ results in an isotopic link.

The splice diagram of a coaxial almost torus link $T_{\left(m_{1}, n_{1}\right), \ldots,\left(m_{r}, n_{r}\right)}$ is given as follows. Suppose that $m_{i+1} / n_{i+1}=m_{i+2} / n_{i+2}=\cdots=m_{i+s} / n_{i+s}=p / q$, where $i, s$ are chosen so that $s \geq 1$ is maximal and $\operatorname{gcd}(p, q)=1$. Define $d_{1}, \ldots, d_{s}$ so that $\left(m_{i+j}, n_{i+j}\right)=\left(d_{j} p, d_{j} q\right)$ for $j=1,2, \ldots, s$. Then the splice diagram will contain $1+\#\left\{j \mid d_{j}>1\right\}$ nodes, arranged as in Figure $14(\mathrm{a})$. We place a node $N$ in the left column incident to $s+2$ edges. For each $j=1,2, \ldots, s$, if $d_{j}=1$ then we add an edge connecting $N$ to an arrowhead leaf in the right column. Otherwise, we draw an edge connecting $N$ to another node in the right column with three edges labeled $\left(d_{j} p q+1,1, d_{j}\right)$ connecting it to $N$, an arrowhead leaf, and a bulletpoint leaf, respectively.

We also create two vertical edges labeled $q$ and $p$ emanating from $N$ up and down, respectively. The resulting pieces are then connected to each other using these vertical edges, ordered from top to bottom according to decreasing radii of the tori. For example, the splice diagram of $T_{(3,2),(6,4),(6,4),(6,15),(2,5),(2,5)}$ is shown in Figure 14(b), where the two slopes are $p / q=3 / 2$ and $p / q=2 / 5$.


Figure 14. Constructing the splice diagram of a coaxial almost torus link.

Proposition 8.2. The coaxial almost torus link $T_{\left(m_{1}, n_{1}\right), \ldots,\left(m_{r}, n_{r}\right)}$ is isotopic to the link $L_{C}$, where $C=C_{\left(m_{1}, n_{1}\right), \ldots,\left(m_{r}, n_{r}\right)}=\left[C_{1} C_{2} \cdots C_{r}\right]$ is a piecewise almost linear curve, and each $C_{i}$ is an $\left(m_{i}, n_{i}\right)$-almost linear curve.

The coaxial almost torus link $T_{\left(m_{1}, n_{1}\right), \ldots,\left(m_{r}, n_{r}\right)}$ is called $\mathbb{Z}$-convex if $C_{\left(m_{1}, n_{1}\right), \ldots,\left(m_{r}, n_{r}\right)}$ is $\mathbb{Z}$ convex. This is the case if and only if $\frac{m_{1}}{n_{1}} \geq \frac{m_{2}}{n_{2}} \geq \cdots \geq \frac{m_{r}}{n_{r}}$; see (1.13).
Proposition 8.3. $\mathbb{Z}$-convex coaxial almost torus links are algebraic.
Proof. According to [EN85, Theorem 9.4], for each edge connecting two nodes $A$ and $B$, we need to check the inequality $x y>\prod_{i} z_{i}$, where $x$ and $y$ are the two labels on the edge, and $z_{i}$-s are the other labels on edges incident to either $A$ or $B$. This inequality follows from the $\mathbb{Z}$-convexity condition.

## Appendix A. Examples

Example A.1. Table 1 lists $F_{C}$ for all curves $C$ from $(0,0)$ to $(m, n)$ with $1 \leq m, n \leq 3$.
Example A.2. Let $m=n=3$ and let $C$ be the curve in Figure 4(c). It is the unique primitive curve from $(0,0)$ to $(3,3)$ which is not $\mathbb{Z}$-convex; cf. Table 1. Moreover, the associated symmetric function $F_{C}$ is not Schur positive. Even though $C$ is not convex, it turns out that the associated link $L_{C}$ is still a positroid link. Namely, it is the smallest known

[^10]

Figure 15. The smallest ${ }^{12}$ primitive convex curve $C$ (shown together with the lattice path $\mathcal{P}_{C}$ ) such that the EHA superpolynomial $\mathcal{P}_{C}^{\mathcal{E}}$ is not $q, t$-unimodal; see Example A.3.
positroid link (associated to a positroid variety in the Grassmannian $\operatorname{Gr}(7,14)$ ) whose odd KR homology does not vanish; see [GL20, Example 4.21]. The coefficient of $s_{3}$ in $F_{C}$ is

$$
q^{4}+q^{3} t+q^{2} t^{2}+q t^{3}+t^{4}+q^{2} t+q t^{2}-q t
$$

By contrast, the top $a$-degree coefficient of $\mathcal{P}_{L_{C}}^{K R}$, computed in [GL20, Example 4.21], is

$$
q^{4}+q^{3} t+q^{2} t^{2}+q t^{3}+t^{4}+q^{2} t+q t^{2}-(q t)^{\frac{3}{2}}
$$

Example A.3. The following example was discovered by A. Mellit and communicated to us by M. Mazin. Consider the primitive curve $C$ in Figure 15, shown together with the highest lattice path

$$
\mathcal{P}_{C}=R R R U R R R U R U R R U U R U U
$$

below $C$; cf. Definition 1.3. The coefficient of $s_{m}$ in $F_{C}$ is given by

$$
\begin{align*}
& q^{16}+q^{15} t+q^{14} t^{2}+q^{13} t^{3}+q^{12} t^{4}+q^{11} t^{5}+q^{10} t^{6}+q^{9} t^{7}+q^{8} t^{8}+q^{7} t^{9}+q^{6} t^{10}+q^{5} t^{11} \\
& +q^{4} t^{12}+q^{3} t^{13}+q^{2} t^{14}+q t^{15}+t^{16}+q^{14} t+q^{13} t^{2}+q^{12} t^{3}+q^{11} t^{4}+q^{10} t^{5}+q^{9} t^{6}+q^{8} t^{7} \\
& +q^{7} t^{8}+q^{6} t^{9}+q^{5} t^{10}+q^{4} t^{11}+q^{3} t^{12}+q^{2} t^{13}+q t^{14}+q^{13} t+2 q^{12} t^{2}+2 q^{11} t^{3}+2 q^{10} t^{4} \\
& +2 q^{9} t^{5}+2 q^{8} t^{6}+2 q^{7} t^{7}+2 q^{6} t^{8}+2 q^{5} t^{9}+2 q^{4} t^{10}+2 q^{3} t^{11}+2 q^{2} t^{12}+q t^{13}  \tag{A.1}\\
& +q^{12} t+3 q^{11} t^{2}+4 q^{10} t^{3}+4 q^{9} t^{4}+4 q^{8} t^{5}+4 q^{7} t^{6}+4 q^{6} t^{7}+4 q^{5} t^{8}+4 q^{4} t^{9} \\
& +4 q^{3} t^{10}+3 q^{2} t^{11}+q t^{12}+2 q^{10} t^{2}+5 q^{9} t^{3}+6 q^{8} t^{4}+6 q^{7} t^{5}+5 q^{6} t^{6}+6 q^{5} t^{7} \\
& +6 q^{4} t^{8}+5 q^{3} t^{9}+2 q^{2} t^{10}+2 q^{8} t^{3}+5 q^{7} t^{4}+8 q^{6} t^{5}+8 q^{5} t^{6}+5 q^{4} t^{7}+2 q^{3} t^{8} .
\end{align*}
$$

The terms $6 q^{7} t^{5}+5 q^{6} t^{6}+6 q^{5} t^{7}$ highlighted in red violate the $q, t$-unimodality property of GL20, Theorem 1.5]. Since $C$ is convex, by the results of [GL21, GL22], we see that $L_{C}$ is a positroid knot. The right-hand side of (1.16) was shown to be $q, t$-unimodal in [GL20]. Therefore, 1.16 cannot hold for $C$. Moreover, the top $a$-degree coefficient of the HOMFLY polynomial $\mathcal{P}_{L_{C}}^{\text {HOMFLY }}$ of the link $L_{C}$ is not parity-unimodal:

$$
\begin{aligned}
\mathcal{P}_{L_{C}}^{\mathrm{HOMFLY}}= & \left(q^{32}+q^{30}+q^{29}+2 q^{28}+2 q^{27}+3 q^{26}+4 q^{25}+5 q^{24}+5 q^{23}+8 q^{22}+7 q^{21}+9 q^{20}\right. \\
& +10 q^{19}+9 q^{18}+13 q^{17}+8 q^{16}+13 q^{15}+9 q^{14}+10 q^{13}+9 q^{12}+7 q^{11}+8 q^{10} \\
& \left.+5 q^{9}+5 q^{8}+4 q^{7}+3 q^{6}+2 q^{5}+2 q^{4}+q^{3}+q^{2}+1\right) \frac{1}{a^{32}}+\cdots .
\end{aligned}
$$



| $C$ |  |  | $F_{C}$ |
| :---: | :---: | :---: | :---: |
|  | Y | Y | $s_{3}$ |
|  | Y | Y | $s_{21}+(q+t) s_{3}$ |
|  | Y | Y | $(q+t) s_{21}+\left(q^{2}+q t+t^{2}\right) s_{3}$ |
|  | Y | Y | $(q+t) s_{21}+\left(q^{2}+q t+t^{2}\right) s_{3}$ |
|  | Y | Y | $\begin{gathered} s_{111}+\left(q^{2}+q t+t^{2}+q+t\right) s_{21} \\ +\left(q^{3}+q^{2} t+q t^{2}+t^{3}+q t\right) s_{3} \end{gathered}$ |
|  | N | N | $\begin{gathered} (q+t-1) s_{111}+\left(q^{3}+q^{2} t+q t^{2}+t^{3}+q^{2}+2 q t+t^{2}-q-t\right) s_{21} \\ +\left(q^{4}+q^{3} t+q^{2} t^{2}+q t^{3}+t^{4}+q^{2} t+q t^{2}-q t\right) s_{3} \end{gathered}$ |
|  | Y | Y | $s_{21}+(q+t-q t) s_{3}$ |
|  | N | N | $\begin{aligned} & (q+t-1-q t) s_{111}+\left(q^{3}+t^{3}+q^{2}+2 q t+t^{2}-q-t-q^{3} t-q^{2} t^{2}-q t^{3}\right) s_{21} \\ & \quad+\left(q^{4}+q^{3} t+q t^{3}+t^{4}+q^{2} t+q t^{2}-q t-q^{4} t-q^{3} t^{2}-q^{2} t^{3}-q t^{4}\right) s_{3} \end{aligned}$ |
|  | Y | Y | $\begin{gathered} (q+t-q t) s_{21} \\ +\left(q^{2}+q t+t^{2}-q^{2} t-q t^{2}\right) s_{3} \end{gathered}$ |
|  | Y | Y | $\begin{gathered} s_{111}+\left(q^{2}+q t+t^{2}+q+t-q^{2} t-q t^{2}\right) s_{21} \\ +\left(q^{3}+q^{2} t+q t^{2}+t^{3}+q t-q^{3} t-q^{2} t^{2}-q t^{3}\right) s_{3} \end{gathered}$ |
|  | Y | Y | $\begin{gathered} s_{111}+\left(q^{2} t^{2}+q^{2}+q t+t^{2}+q+t-2 q^{2} t-2 q t^{2}\right) s_{21} \\ +\left(q^{3} t^{2}+q^{2} t^{3}+q^{3}+q^{2} t+q t^{2}+t^{3}+q t-2 q^{3} t-2 q^{2} t^{2}-2 q t^{3}\right) s_{3} \end{gathered}$ |
|  | Y | Y | $\begin{gathered} (q+t-q t) s_{21} \\ +\left(q^{2}+q t+t^{2}-q^{2} t-q t^{2}\right) s_{3} \end{gathered}$ |
|  | Y | Y | $\begin{gathered} s_{111}+\left(q^{2}+q t+t^{2}+q+t-q^{2} t-q t^{2}\right) s_{21} \\ +\left(q^{3}+q^{2} t+q t^{2}+t^{3}+q t-q^{3} t-q^{2} t^{2}-q t^{3}\right) s_{3} \end{gathered}$ |

Table 1. The symmetric functions $F_{C}$ for all monotone curves $C$ with $1 \leq$ $m, n \leq 3$. Here, $\mathrm{Y} / \mathrm{N}$ indicates whether each curve is $s$-positive (i.e., has $(q, t)$ Schur positive series (1.14)) and $\mathbb{Z}$-convex (Definition 1.12).
(By (1.19), this coefficient is obtained by plugging $t=q^{-1}$ into (A.1) and multiplying the result by $q^{16} / a^{32}$.) Combining this with the results of [GL20], we see that the odd KR homology of $L_{C}$ cannot vanish. This disproves [GL21, Conjecture 7.1(ii,iv)].

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Department of Mathematics, University of California, Los Angeles, 520 Portola Plaza, Los Angeles, CA 90025, USA

Email address: galashin@math.ucla.edu
Department of Mathematics, University of Michigan, 2074 East Hall, 530 Church Street, Ann Arbor, MI 48109-1043, USA

Email address: tfylam@umich.edu


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[^1]:    ${ }^{1}$ Strictly speaking, we consider framed links, for which there is an extra framing change relation involving another variable $v$; see 5.1). All our links are assumed to have blackboard framing; see Section 5.1 .

[^2]:    ${ }^{2}$ More precisely, the link invariant $\mathcal{P}_{L_{C}}^{\mathrm{KR}}(a, q, t)$ differs from the triply-graded Poincaré series encoding the dimensions of KR homology by a monomial in $a, q^{1 / 2}, t^{1 / 2}$.

[^3]:    ${ }^{3}$ The formula for $\phi_{N}^{\prime}\left(T_{i}\right)$ in [SV13, Section 1.4] appears to contain a typo: $t^{1 / 2} s_{i}$ should be replaced with $t^{-1 / 2} s_{i}$. Additionally, below [SV13, Equation (1.12)], the authors set $y_{1}=1$ as opposed to $y_{1}=q^{-1}$. However, in order for $P_{1,0}^{\infty}$ to act by multiplication by $p_{1}$ as claimed in [SV13, Proposition 1.4], one needs to set $y_{1}=q^{-1}$.
    ${ }^{4}$ Note that both [SV11, Section 2.1] and GN15, Equation (13)] contain the same typo in the formulas 2.14-2.15): their $T_{i}$ should be $T_{1}$.
    ${ }^{5}$ We thank José Simental for discussions regarding the relation $\left(\tau_{+} \tau_{-}^{-1} \tau_{+}\right)^{4}=\mathrm{id}$.

[^4]:    ${ }^{6}$ An equivalent description of $\mathcal{E}_{q, t}^{+}$is given in BGLX15. (cf. Section 7.1.3), where the formulas for the action on $\Lambda_{q, t}$ are manifestly $(q, t)$-symmetric.

[^5]:    ${ }^{7}$ Comparing the proof of [GW23, Proposition 2.6] with GW23, Lemma 2.5], we see that $h_{n}$ in GW23, Proposition 2.6] should be replaced with $e_{n}$. This mistake appears to affect some further results in GW23, Section 2]. In particular, the $(-1)^{k}$ in [GW23, Corollary 2.22] should be omitted.

[^6]:    ${ }^{8}$ For instance, the substitution $(q, t) \mapsto\left(q^{-1}, t\right)$ comes from comparing 3.2 to the definition of $\alpha_{i}$ in MS17, Section 5].

[^7]:    ${ }^{9}$ Letting $C_{\boldsymbol{x},+}$ and $C_{\boldsymbol{x},-}$ be the shifts of $C_{\boldsymbol{x}}$ as in Section 1.3 , we see that $C_{\boldsymbol{x},+}^{\mathbb{T}-\mathbb{D}}$ is a $\sigma_{1} \sigma_{2} \cdots \sigma_{d-1}$-decoration of $C_{\boldsymbol{x}_{0}}^{\mathbb{T}}$. However, the same is not true for $C_{\boldsymbol{x},-}^{\mathbb{T}-\mathbb{D}}$, since the puncture "gets stuck" inside the decoration; see Figure 11

[^8]:    ${ }^{10}$ In $\left[\mathrm{BHM}^{+} 21\right]$, the operator $\mathbf{D}_{k}$ was denoted $D_{k}$. It differs from the operator denoted $\mathbf{D}_{k}$ in BGLX15, Equation (2.1)] by a sign $(-1)^{k}$; cf. the discussion after $\left[\mathrm{BHM}^{+} 21\right.$, Equation (35)].

[^9]:    ${ }^{11}$ Here we have inserted $\epsilon$ to keep the curve $x$-monotone.

[^10]:    ${ }^{12}$ Here $(m, n)=(10,7)$, and one can check that for any primitive convex curve with $m+n<17$, the EHA superpolynomial is $q, t$-unimodal.

